

AN N-DIMENSIONAL FUNCTION - ONLY CODE FOR NON-LINEAR UNCONSTRAINED OPTIMIZATION

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1. Introduction. -

The present report documents a code, compiled in the two versions OTLSSS and OTLSSD, for minimizing n-dimensional functions.

This routine is to be inserted in a library which will be provided from the CNR, SOFMAT Project, to solve a wide range of mathematical and statistical problems arising in a variety of fields such as applied mathematics, physics, chemistry, engineering, biology, economics, managerial science, market research, government, agricultural and medical research.

Such library will be available in FORTRAN language for minicomputers, namely for PDP 11/40. It will cater for both the novice and the experienced programmer, therefore the documentation of all routines must be comprehensive, detailed and clear. Moreover the selection and the implementation of the algorithms and the choice of the test problems must reflect the aim of the library which tends to possess efficiency, usefulness, accuracy and reliability.

2. Routine document. -

The two codes OTLSSS and OTLSSD, written in FORTRAN language for the PDP 11/40 computer, are two versions of the same program respectively compiled in single and in double precision. This program has been developed to solve the problem of non-linear unconstrained optimisation having the following mathematical description

$$\min_{x \in \mathbb{R}^n} F(x)$$

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The first three characters OTL refer to the field of unconstrained optimization, the fourth character S mentions the used Sutti's method, the fifth S indicates that this one is the second implementation of Sutti's method, and the final S and D distinguish the version in single precision from the version in double precision. OTLSSS and OTLSSD and the related subroutines differ only for same declarative statements and for same library functions.

OTLSSS and OTLSSD read and print the following input parameters: dimension of the variable space, initial approximation of the minimizer, stopping tolerances, initial step lenght of the line search, maximum allowed number of function evaluations. Moreover these routines read the index of printing, then they call respectively the subroutines CNS and CNSD.

CNS and CNSD search for a minimum of a n-dimensional function by the Sutti's method, using function values only (1). This method is intended for quadratic, strictly convex and non-convex functions (1,2,3). It computes a sequence of points of descent by moving along sets of n linearly normalized independent directions. The initial set, consisting of the n coordinate axes, is modified in order to build mutually conjugate directions with respect to the hessian matrix of a quadratic objective function. CNS calls the subroutines SEARCH and CALFUN and CNSD calls SEARD and CALFUD. SEARCH and SEARD search for a minimum of an one-dimensional function by a method using function values only, which is based on quadratic interpolation (3). The method computes a point set bracketing the minimum of the objective function along the search direction and sets the position of the minimum in the vertex of the interpolating parabole. Safeguards to avoid spurious stationary points are provided. SEARCH and SEARD call respectively CALFUN and CALFUD.

CALFUN and CALFUD compute the function value in a required point. These subroutines must be supplied from the user.

The argument lists are the following:

SUBROUTINE CNS (XA,N,F,DIR,EPS,EPS1,EPS3,EPS4,IFMAX,XMU,IPRINT)

SUBROUTINE CNSD(XA,N,F,DIR,EPS,EPS1,EPS3,EPS4,IFMAX,XMU,IPRINT)

with

XA,real	n-dimensional vector containing, on entry, the user's estimate of the minimizer and, on exit, the computed minimizer;
N,integer	variable specifying the number n of independent variables: N must be assigned before entry;
F,real	variable containing function value in the current point, on exit F contains the estimated value of the minimum;
DIR,real	matrix of the search vectors: DIR is built in OTLSSS and in OTLSSD;
EPS,EPS1,EPS3, EPS4,real	variables containing the accuracies, to be assigned before entry: EPS and EPS1 must be to the relative accuracies to which the minimizer and the minimum are required, EPS4 and EPS3 scale EPS to the different accurancies EPS2 required in the line searches respetively along the 1-st, 2-nd,..., (n-k)-th direction and along the (n-k+1)-th,...,n-th direction. To make consistent these accuracies, EPS4 should be not smaller than 1 and not bigger than 10, while EPS3 should be not smaller than 10^2 and not bigger than 10^3 , whenever EPS and EPS1 are set to 10^{-5} ; To make consistent these accuracies, EPS4 should be not smaller than 1 and not bigger than 10, while EPS3 should be not smaller than 10^2 and not bigger than 10^3 , whenever EPS and EPS1 are set to 10^{-5} ;
IFMAX, integer	variable containing the maximum allowed number of function evaluations: IFMAX must be assigned before entry. It depends from the behaviour and from the dimension of the objective function and from the required accuracies: in the performed proofs IFMAX is set to 10^4 ;
XMU,real	variable containing the initial step lenght for the line search, to be assigned less or equal to 1 before entry;
IPRINT,integer	parameter controlling print as follows: for IPRINT=1 the current values and the final ones of the cycle index, of the iteration index, and of the minimizer and minimum approximations are printed; for IPRINT=0 only the final values are printed.

SUBROUTINE SEARCH (D,IFMAX1,EPS2,X0,N,F0,MU,X,IFUN)

SUBROUTINE SEARD (D,IFMAX1,EPS2,X0,N,F0,MU,X,IFUN)

with

D,real n-dimensional vector to be computed before entry;
IFMAX1,integer variable containing the difference between IFMAX and IFUN to
be computed before entry;
EPS2,real variable containing the accuracy to which the position of the
one-dimensional minimum is required:EPS2 must be calculated
before entry;
X0,real variable containing the actual approximation of the minimizer;
F0,real variable containing the function value in X0;
MU,real variable containing the step lenght on entry;
X,real variable containing the step lenght on exit;
IFUN,integer variable containing the total number of function evaluations;

SUBROUTINE CALFUN (X,N,F,IFUN)

SUBROUTINE CALFUD (X,N,F,IFN)

with

X, real variable containing the point at which the function value is
required;
N,integer variable specifying the number of independent variables;
F,real variable containing the function value in X;
IFUN,integer variable containing the total number of function evaluations.

The lenght of the codes, i.e. the total number of statements in OTLSSS and in
OTLSSD are respectively 309 and 313. The size of the problems for which the codes
has been designed is $n \leq 50$. The related required storage is of 9.132 words
(9.132x16 bits) for OTLSSS and 14.986 words (14.986x16 bits) for OTLSSD. In the
above sums none care is taken or of the subroutine CALFUN or of CALFUD.

The test problems solved by OTLSSS and OTLSSD on the PDP 11/40 of 32K words,
at the Mathematical Institute, University of PARMA (ITALY), were the minimizations
of the following functions:

- 1 - Extended Rosenbrock
- 2 - Extended Powell
- 3 - Oren's Quartic
- 4 - Penalty I
- 5 - More first function
- 6 - Trigonometric
- 7 - More second function
- 8 - Brown almost linear
- 9 - Mancino
- 10 - Watson
- 11 - Penalty II
- 12 - Chebyquad

For the mathematical description of the above functions with the related starting points $x_0 = (x_{0i}), i = 1, \dots, n$, see ref.(4).

The proofs have been performed for $n = 4, 10$ and for $n = 4, 8$ for the Extended Powell function. Moreover the following initial approximations of the minimizer were assumed: $x_0^1 = (x_{0i}), x_0^2 = (x_{0i} + \Delta_i)$ with $\Delta_i = 10^{-3}(1+|x_0|)$ and $x_0^3 = (10 x_{0i}), i = 1, \dots, n$. The other input parameters were assigned as above described.

In the annexed listing 1 and 2 we present the executions of the programs OTLSSS and OTLSSD, with IPRINT = 0, for the sample problem

$$\min_{x_1, x_2} 100(x_2 - x_1^2)^2 + (1-x_1)^2 \quad x_0 = (-1.2, 1)$$

having analytical solution $x_{\min} = (1, 1)$, $F_{\min} = 0$.

The annexed numerical tables 3 and 4 visualize the results obtained by OTLSSS and OTLSSD. The parameter NPROB is the number of the objective function in the above sequence, N is the size of the problem, XZERO indicates which starting vector is tested, CYC is the total number of the performed cycles, ITER the number of the iterations in the final cycle, IFUN the total number of function evaluations and F the computed minimum.

Listing 1

```
C OTLSSS
C QUESTO PROGRAMMA ESEGUE LA MINIMIZZAZIONE DI UNA FUNZIONE OBIETTIVO
C N-DIMENSIONALE NON VINCOLATA CON LA SECONDA IMPLEMENTAZIONE
C DEL METODO DI SUTTI(1975) IN SINGOLA PRECISIONE
C IPRINT=0 PRESENTA LA STAMPA DEI SOLI RISULTATI FINALI
C IPRINT=1 PRESENTA ANCHE LA STAMPA DI RISULTATI INTERMEDI
C N RAPPRESENTA LA DIMENSIONE DEL DOMINIO DELLA FUNZIONE DA MINIMIZZARE
C IFMAX RAPPRESENTA IL MASSIMO NUMERO DI VALUTAZIONI
C DI FUNZIONE CONSENTITO
C XMU RAPPRESENTA IL PASSO INIZIALE PER LA RICERCA DI LINEA
C EPS E' LA PRECISIONE SUL PUNTO DI MINIMO
C EPS1 E' LA PRECISIONE SULLA FUNZIONE
C EPS3,EPS4 SONO I PARAMETRI PER DEDURRE LA PRECISIONE
C MONODIMENSIONALE DALLA PRECISIONE N-DIMENSIONALE
C X RAPPRESENTA IL PUNTO INIZIALE
C DIR RAPPRESENTA LA MATRICE DELLE DIREZIONI DI RICERCA
    DIMENSION X(50),DIR(50,50)
    READ(5,14)IPRINT
14   FORMAT(1I1)
100  READ(5,2)N,IFMAX,XMU,EPS,EPS1
    2   FORMAT(2I5,5F10.5)
        READ(5,3)EPS3,EPS4
    3   FORMAT(F10.3,F10.3)
        READ(5,4)(X(I),I=1,N)
    4   FORMAT(1OF7.3)
        WRITE(6,1)N
    1   FORMAT(1H1,3HN ==,I3)
        WRITE(6,10)IFMAX,XMU
    10  FORMAT(/,1X,7HIFMAX ==,I6,7X,5HXMU ==,E14.7)
        WRITE(6,15)EPS,EPS1
    15  FORMAT(/,1X,5HEPS ==,E13.6,5X,6HEPS1 ==,E13.6)
        WRITE(6,13)EPS3,EPS4
    13  FORMAT(/,1X,5HEPS3==,E13.6,5X,6HEPS4 ==,E13.6)
        WRITE(6,16)
    16  FORMAT(/,1X,2HX=)
        WRITE(6,17)(X(I),I=1,N)
    17  FORMAT(4(2X,E14.7))
        DO 8 I=1,50
        DO 8 J=1,50
    8   DIR(I,J)=0
        DO 9 I=1,50
    9   DIR(I,I)=1
    CALL CNS(X,N,F,DIR,EPS,EPS1,EPS3,EPS4,IFMAX,XMU,IPRINT)
95   STOP
END
```

```
SUBROUTINE CNS(XA,N,F,DIR,EPS,EPS1,EPS3,EPS4,IFMAX,XMU,IPRINT)
C QUESTO SOTTOPROGRAMMA ESEGUE LA RICERCA N-DIMENSIONALE
C ALPHA RAPPRESENTA IL PASSO ARBITRARIO
C DIRL E' IL VETTORE POSTO NELLA L-ESIMA COLONNA DELLA MATRICE DIR
C IFMAX1 RAPPRESENTA IL NUMERO DI VALUTAZIONI DI FUNZIONE
C ANCORA DISPONIBILI
C I E' L'INDICE DI CICLO
C K E' L'INDICE DI ITERAZIONE CHE NON SUPERA N-1
    DIMENSION X(50),XA(50),D(50)
    DIMENSION XA(50),XB(50),XA1(50),DIR(50,50),DIRN(50)
    SC=XMU
    IFUN=0
    CALL CALFUN(XA,N,FA,IFUN)
    I=0
    1  I=I+1
    IF(IPRINT) 32,33,32
32   CONTINUE
    WRITE(6,80)I
80   FORMAT(/,,/,1X,'CICLO I = ',I3)
33   CONTINUE
    K=0
    2  K=K+1
    IF(IPRINT) 34,35,34
34   CONTINUE
    WRITE(6,88)K
88   FORMAT(/,,1X,'ITERAZIONE K = ',I3)
35   CONTINUE
    DO 3 II=1,N
    3  DIRN(II)=DIR(II,N)
    IFMAX1=IFMAX-IFUN
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C MINIMIZZAZIONE LUNGO DIRL CON L=N
  IF(IPRINT)36,37,36
  36 CONTINUE
    WRITE(6,94)(XA(IB),IB=1,N)
  94 FORMAT(1X,2HX=,10E12.5)
    WRITE(6,89)FA
  89 FORMAT(1X,2HF=,E14.7)
    WRITE(6,93)
  93 FORMAT(1X,'MINIMIZZAZIONE MONODIMENSIONALE')
  37 CONTINUE
  EPS2=EPS*EPS3
  CALL SEARCH(DIRN,IFMAX1,EPS2,XA,N,FA,XMU,SC,IFUN)
  IF(IPRINT)38,39,38
  38 CONTINUE
    WRITE(6,94)(XA(IB),IB=1,N)
    WRITE(6,89) FA
  39 CONTINUE
    IF(IFUN.GT.IFMAX) GO TO 1001
    L=0
  4 L=L+1
C ESECUZIONE DEL PASSO ALPHA LUNGO DIRL L=1,...,N-K
  IF(L.GT.(N-K)) GO TO 45
  DO 41 II=1,N
  41 DIRN(II)=DIR(II,L)
    ALPHA=AMAX1(ABS(SC)*0.5,0.0001)
  DO 42 II=1,N
  42 XA1(II)=XA(II)+ALPHA*DIRN(II)
    CALL CALFUN(XA1,N,FA1,IFUN)
    IF(IFUN.GT.IFMAX) GO TO 1001
    AMAX=AMAX1(EPS1,EPS1*ABS(FA))
    IF((FA-FA1).GT.AMAX*0.001) GO TO 43
    DO 44 II=1,N
      DIRN(II)=-DIRN(II)
  44 XA1(II)=XA(II)+ALPHA*DIRN(II)
    CALL CALFUN(XA1,N,FA1,IFUN)
    IF(IFUN.GE.IFMAX) GO TO 1001
    AMAX=AMAX1(EPS1,EPS1*ABS(FA))
    IF((FA-FA1).GT.AMAX*0.001) GO TO 43
    GO TO 4
  45 CONTINUE
C MINIMIZZAZIONE LUNGO DIRL CON L=1...,N-K PER FALLIMENTO PASSO ALPHA
  L=0
  5 L=L+1
  IF(L.GT.(N-K)) GO TO 1000
  DO 51 II=1,N
  51 DIRN(II)=DIR(II,L)
  DO 551 II=1,N
  551 X0(II)=XA(II)
  FO=FA
  IFMAX1=IFMAX-IFUN
  EPS2=EPS*EPS4
  CALL SEARCH(DIRN,IFMAX1,EPS2,X0,N,FO,XMU,SC,IFUN)
  IF(IPRINT) 31,433,31
  31 CONTINUE
  WRITE(6,95)
  95 FORMAT(1X,'MINIMIZZAZIONE MONODIMENSIONALE IN QUANTO FALLITA LA RI-
ACERCA DI UN PASSO ARBITRARIO DI DISCESA')
    WRITE(6,94)(X0(IB),IB=1,N)
    WRITE(6,89)FO
  433 CONTINUE
  IF(IFUN.GE.IFMAX) GO TO 1001
C ESECUZIONE DEI CRITERI D'ARRESTO
  IF(ABS(SC).GT.EPS) GO TO 113
  AMAX=AMAX1(EPS1,EPS1*ABS(FA))
  IF((FA-FO).GT.AMAX) GO TO 113
  GO TO 5
  113 CONTINUE
  DO 553 II=1,N
  553 XA1(II)=X0(II)
  FA1=FO
  GO TO 66
  43 CONTINUE
  IF(IPRINT)20,21,20
  20 CONTINUE
  WRITE(6,99)
  99 FORMAT(1X,'RICERCA RIUSCITA DI UN PASSO ARBITRARIO DI DISCESA')
  WRITE(6,94)(XA1(IB),IB=1,N)
  WRITE(6,89)FA1
  21 CONTINUE
  66 CONTINUE
C MINIMIZZAZIONI LUNGO DIRL CON L=N-K+1...,N
  J=N-K
  6 J=J+1
  DO 61 II=1,N
  61 DIRN(II)=DIR(II,J)
  IFMAX1=IFMAX-IFUN

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EPS2=EPS*EPS3
CALL SEARCH(DIRN,IFMAX1,EPS2,XA1,N,FA1,XMU,SC,IFUN)
IF(IPRINT)22,23,22
22 CONTINUE
WRITE(6,93)
WRITE(6,94)(XA1(IB),IB=1,N)
WRITE(6,89) FA1
23 CONTINUE
IF(IFUN.GE.IFMAX) GO TO 1001
IF(J.EQ.N) GO TO 62
GO TO 6
62 CONTINUE
C CALCOLO DELLA NUOVA MATRICE DELLE DIREZIONI DI RICERCA
XMOD=0.0
DO 8 II=1,N
8 XMOD=XMOD+(XA1(II)-XA(II))**2
XMOD=SQRT(XMOD)
DO 7 JJ=1,N
IF(JJ.LT.L) GO TO 7
IF(JJ.EQ.N) GO TO 71
DO 72 II=1,N
72 DIR(II,JJ)=DIR(II,JJ+1)
GO TO 7
71 DO 73 II=1,N
73 DIR(II,JJ)=XA1(II)-XA(II)
7 CONTINUE
DO 81 II=1,N
XA(II)=XA1(II)
81 DIR(II,N)=DIR(II,N)/XMOD
FA=FA1
147 IF(K.EQ.(N-1)) GO TO 1
GO TO 2
1001 WRITE(6,104)
104 FORMAT(1H1,14HIFMAX EXCEEDED)
GO TO 1002
1000 WRITE(6,100)IFUN,I,K
100 FORMAT(/,,1X,19HOPTIONAL FOUND AFTER,I5,15HFUNCTION CALLS,,,
1I5,7HCYCLES,,I5,11HSIMPLE IER,) 
1002 CONTINUE
WRITE(6,101)
101 FORMAT(/,1X,2HX=)
WRITE(6,102) (XA(I),I=1,N)
102 FORMAT(4(2X,E14.7))
WRITE(6,103) FA
103 FORMAT(/,1X,24HMINIMUM FUNCTION VALUE =,E14.7)
RETURN
END

```

```

SUBROUTINE SEARCH(D,IFMAX1,EPS2,X0,N,F0,MU,X,IFUN)
C QUESTO SOTTOPROGRAMMA ESEGUE LA RICERCA MONODIMENSIONALE
C EPS2 E' LA PRECISIONE NELLA RICERCA MONODIMENSIONALE
C MU RAPPRESENTA IL PASSO INIZIALE PER LA RICERCA MONODIMENSIONALE
DIMENSION X0(50),X(50),X1(50)
REAL MU
ITEST=3
MU=AMAX1(ABS(X),1.5*EPS2)
XSTEP=SIGN(MU,X)
X=0.0
F=F0
C CALCOLO DEI PUNTI DA INTERPOLARE
51 GO TO 2000
2100 GO TO(1,2,335,336),ITEST
1 DO 70 I=1,N
70 X1(I)=X0(I)+X*X*D(I)
CALL CALFUN(X1,N,F,IFUN)
GO TO 51
2 CONTINUE
C CALCOLO DEL MINIMO MONODIMENSIONALE
DO 377 I=1,N
377 X1(I)=X0(I)+DV*D(I)
CALL CALFUN(X1,N,FV,IFUN)
IF(F-FV)50,50,59
59 F=FV
X=DV
50 IF(F.LT.F0) GO TO 60
F=F0
X=0.0
123 FORMAT (1X,I4)
GO TO 2200
60 DO 30 I=1,N
30 X0(I)=X0(I)+X*D(I)
F0=F
GO TO 2200

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- 2 -

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335 CONTINUE
GO TO 50
336 WRITE(6,122)
122 FORMAT(1H1,14HIFMAX EXCEEDED)
GO TO 50
2000 CONTINUE
GO TO(91,222,222),ITEST
222 IS=6-ITEST
ITEST=1
IINC=1
XINC=XSTEP+XSTEP
MC=IS-3
IF(MC) 4,4,15
3 MC=MC+1
IF(IFMAX1-MC) 12,15,15
C C CASO IN CUI E' STATO RAGGIUNTO IL MASSIMO NUMERO DI VALUTAZIONE
C DI FUNZIONE
12 ITEST=4
43 X=DB
F=FB
IF(FB-FC) 15,15,44
44 X=DC
F=FC
15 GO TO 2100
91 GO TO (5,6,7,8),IS
3 IS=3
4 DC=X
FC=F
X=X+XSTEP
GO TO 3
C CONFRONTO TRA VALORE DELLA FUNZIONE NEL PUNTO INIZIALE E NEL
C PUNTO ATTUALE
7 IF(FC-F) 9,10,11
10 X=X+XINC
XINC=XINC+XINC
GO TO 3
9 DB=X
FB=F
XINC=-XINC
GO TO 13
11 DB=DC
FB=FC
DC=X
FC=F
13 X=DC+DC-DB
IS=2
GO TO 3
6 DA=DB
LB=DC
FA=FB
FB=FC
32 DC=X
FC=F
GO TO 14
5 IF(FB-FC) 16,17,17
17 IF(F-FB) 18,32,32
18 FA=FB
DA=DS
19 FB=F
DB=X
GO TO 14
16 IF(FA-FC) 21,21,20
20 XINC=FA
FA=FC
FC=XINC
XINC=DA
DA=DC
DC=XINC
21 XINC=DC
IF((DV-DB)*(DV-DC)) 32,22,22
22 IF(F-FA) 23,24,24
23 FC=FB
DC=DB
GO TO 19
24 FA=F
DA=X
14 IF(FB-FC) 25,25,29
25 IINC=2
XINC=DC
IF(FB-FC) 29,45,29
C CALCOLO DELL'ASCISSA DEL VERTICE DELLA PARABOLA INTERPOLANTE
29 DV=(FA-FB)/(DA-DB)-(FA-FC)/(DA-DC)
IF(DV*(DB-DC)) 33,33,37
37 DV=0.5*(DB+DC-(FB-FC)/DV)

```

```

C ESECUZIONE DEL CRITERIO DI ARRESTO CON PRECISIONE ASSOLUTA O RELATIVA
56 IF(ABS(DV-X)-ABS(EPS2))34,34,35
35 IF(ABS(DV-X)-ABS(I*EPS2)) 34,34,36
34 ITEST=2
GO TO 43
36 IS=1
X=DV
IF((DA-DC)*(DC-DV))3,26,38
38 IS=2
GO TO (3,40),IINC
33 IS=2
GO TO (41,42),IINC
41 X=DC
GO TO 10
40 IF(ABS(XINC-X)-ABS(X-DC)) 42,42,3
42 X=0.5*(XINC+DC)
IF((XINC-X)*(X-DC)) 26,26,3
45 X=0.5*(DB+DC)
IF((DB-X)*(X-DC)) 26,26,3
26 ITEST=3
GO TO 43
2200 CONTINUE
RETURN
END

```

```

SUBROUTINE CALFUN(X,N,F,IFUN)
C QUESTO SOTTOPROGRAMMA CALCOLA LA FUNZIONE DA MINIMIZZARE NEL PUNTO
C ATTUALE
C X RAFFRESENTA IL PUNTO IN CUI VIENE CALCOLATA LA FUNZIONE
C N RAFFRESENTA LA DIMENSIONE DEL DOMINIO DELLA FUNZIONE DA MINIMIZZARE
C F RAFFRESENTA LA FUNZIONE OGGETTIVO
C IFUN RAFFRESENTA IL NUMERO DI VALUTAZIONI DI FUNZIONE ESEGUITE
DIMENSION X(50)
F=100.*(X(2)-X(1))*X(1))*(X(2)-X(1)*X(1))+(1-X(1))*(1-X(1))
IFUN=IFUN+1
1000 CONTINUE
RETURN
END

```

N = 2

```

IFMAX = 10000      XMU = 0.5000000E 00
EPS = 0.100000E-04    EPS1 = 0.100000E-04
EPS3= 0.100000E 03    EPS4 = 0.100000E 01
X=
-0.1200000E 01    0.1000000E 01

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```

OPTIMUM FOUND AFTER 283FUNCTION CALLS, 12CYCLES, 1SIMPLE IER,
X=
0.1000002E 01    0.1000005E 01
MINIMUM FUNCTION VALUE = 0.2684430E-10

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Listing 2

```
C OTLSSD
C QUESTO PROGRAMMA ESEGUE LA MINIMIZZAZIONE DI UNA FUNZIONE OBIETTIVO
C N-DIMENSIONALE NON VINCOLATA CON LA SECONDA IMPLEMENTAZIONE
C DEL METODO DI SUTTI(1975) IN DOPPIA PRECISIONE.
C IPRINT=0 PRESENTA LA STAMPA DEI SOLI RISULTATI FINALI
C IPRINT=1 PRESENTA ANCHE LA STAMPA DI RISULTATI INTERMEDI
C N RAFFRESENTA LA DIMENSIONE DEL DOMINIO DELLA FUNZIONE DA MINIMIZZARE
C IFMAX RAFFRESENTA IL MASSIMO NUMERO DI VALUTAZIONI
C DI FUNZIONE CONSENTITO
C XMU RAFFRESENTA IL PASSO INIZIALE PER LA RICERCA DI LINEA
C EPS E' LA PRECISIONE SUL FUNTO DI MINIMO
C EPS1 E' LA PRECISIONE SULLA FUNZIONE
C EPS3,EPS4 SONO I PARAMETRI PER DEDURRE LA PRECISIONE MONODIMENTONALE
C DALLA PRECISIONE N-DIMENSIONALE
C X RAFFRESENTA IL FUNTO INIZIALE
C DIR RAFFRESENTA LA MATRICE DELLE DIREZIONI DI RICERCA
DIMENSION X(50),DIR(50,50)
DOUBLE PRECISION X,F,DIR,XMU,EPS,EPS1
READ(5,14)IPRINT
14 FORMAT(II)
100 READ(5,2)N,IFMAX,XMU,EPS,EPS1
2 FORMAT(2I5,3D15.5)
READ(5,4)EPS3,EPS4
READ(5,4)(X(I),I=1,N)
4 FORMAT(4D15.5)
WRITE(6,1)N
1 FORMAT(1H1,3HN =,I3)
WRITE(6,10)IFMAX,XMU
10 FORMAT(//,1X,7HIFMAX =,I6,7X,5HXMU =,D14.7)
WRITE(6,15)EPS,EPS1
15 FORMAT(//,1X,5HEPS =,D13.6,5X,6HEPS1 =,D13.6)
WRITE(6,13)EPS3,EPS4
13 FORMAT(//,1X,5HEPS3=,D13.6,5X,6HEPS4 =,D13.6)
WRITE(6,16)
16 FORMAT(//,1X,2HX=)
WRITE(6,17)(X(I),I=1,N)
17 FORMAT(4(2X,D14.7))
DO 8 I=1,50
DO 8 J=1,50
8 DIR(I,J)=0
DO 9 I=1,50
9 DIR(I,I)=1
CALL CNSD(X,N,F,DIR,EPS,EPS1,EPS3,EPS4,IFMAX,XMU,IPRINT)
95 STOP
END
```

```
SUBROUTINE CNSD(XA,N,F,DIR,EPS,EPS1,EPS3,EPS4,IFMAX,XMU,IPRINT)
C QUESTO SOTTOPROGRAMMA ESEGUE LA RICERCA N-DIMENSIONALE
C DIRL E' IL VETTORE POSTO NELLA L-ESIMA COLONNA DELLA MATRICE DIR
C ALPHA RAFFRESENTA IL PASSO ARBITRARIO
C IFMAX1 RAFFRESENTA IL NUMERO DI VALUTAZIONI DI FUNZIONE
C ANCORA DISPONIBILI
C I E' L'INDICE DI CICLO
C K E' L'INDICE DI ITERAZIONE CHE NON SUPERA N-1
DIMENSION X(50),X0(50),D(50)
DIMENSION XA(50),XB(50),XA1(50),DIR(50,50),DIRN(50)
DOUBLE PRECISION XA,F,DIR,EPS,EPS1,XMU
DOUBLE PRECISION X,X0,D,XB,XA1,DIRN,SC,EPS2,FA,ALPHA,FA1
DOUBLE PRECISION AMAX,FO,XMOD
SC=XMU
IFUN=0
CALL CALFUD(XA,N,FA,IFUN)
I=0
1 I=I+1
IF(IPRINT) 32,33,32
32 CONTINUE
WRITE(6,80)I
80 FORMAT(//,/,/,/,/,1X,'CICLO I=',I3)
33 CONTINUE
K=0
2 K=K+1
IF(IPRINT) 34,35,34
34 CONTINUE
WRITE(6,88)K
88 FORMAT(//,1X,'ITERAZIONE K=',I3)
35 CONTINUE
```

```

DO 3 II=1,N
3 DIRN(II)=DIR(II,N)
IFMAX1=IFMAX-IFUN
C MINIMIZZAZIONE LUNGO DIRL CON L=N
IF(IPRINT)36,37,36
36 CONTINUE
WRITE(6,94)(XA(IB),IB=1,N)
94 FORMAT(IX,2HX,,4D15.5)
WRITE(6,89)FA
89 FORMAT(1X,2HF,,D30.20)
WRITE(6,93)
93 FORMAT(1X,'MINIMIZZAZIONE MONODIMENSIONALE')
37 CONTINUE
EPS2=EPS*EPS3
CALL SEARD(DIRN,IFMAX1,EPS2,XA,N,FA,XMU,SC,IFUN)
IF(IPRINT)38,39,38
38 CONTINUE
WRITE(6,94)(XA(IB),IB=1,N)
WRITE(6,89) FA
39 CONTINUE
IF(IFUN.GT.IFMAX) GO TO 1001
L=0
4 L=L+1
IF(L.GT.(N-K)) GO TO 45
C ESECUZIONE DEL PASSO ALPHA LUNGO DIRL L=1,...,N-K
DO 41 II=1,N
41 DIRN(II)=DIR(II,L)
ALPHA=DMAX1(DABS(SC)*0.5,1.D-4)
DO 42 II=j,N
42 XA1(II)=XA(II)+ALPHA*DIRN(II)
CALL CALFUD(XA1,N,FA1,IFUN)
IF(IFUN.GT.IFMAX) GO TO 1001
AMAX=DMAX1(EPS1,EPS1*DARS(FA))
IF((FA-FA1).GT.AMAX*0.001) GO TO 43
DO 44 II=1,N
DIRN(II)=DIRN(II)
44 XA1(II)=XA(II)+ALPHA*DIRN(II)
CALL CALFUD(XA1,N,FA1,IFUN)
IF(IFUN.GE.IFMAX) GO TO 1001
AMAX=DMAX1(EPS1,EPS1*DABS(FA))
IF((FA-FA1).GT.AMAX*0.001) GO TO 43
GO TO 4
45 CONTINUE
C MINIMIZZAZIONE LUNGO DIRL CON L=1...,N-K PER FALLIMENTO PASSO ALPHA
L=0
5 L=L+1
IF(L.GT.(N-K)) GO TO 1000
DO 51 II=1,N
51 DIRN(II)=DIR(II,L)
DO 551 II=1,N
551 XO(II)=XA(II)
FO=FA
IFMAX1=IFMAX-IFUN
EPS2=EPS*EPS4
CALL SEARD(DIRN,IFMAX1,EPS2,XO,N,FO,XMU,SC,IFUN)
IF(IPRINT) 31,433,31
31 CONTINUE
WRITE(6,95)
95 FORMAT(IX,'MINIMIZZAZIONE MONODIMENSIONALE IN QUANTO FALLITA LA RI
ACERCA DI UN PASSO ARBITRARIO DI DISCESA')
WRITE(6,94)(XO(IB),IB=1,N)
WRITE(6,89)FO
433 CONTINUE
IF(IFUN.GE.IFMAX) GO TO 1001
C ESECUZIONE DEI CRITERI D'ARRESTO
IF(DABS(SC).GT.EPS) GO TO 113
AMAX=DMAX1(EPS1,EPS1*DABS(FA))
IF((FA-FO).GT.AMAX) GO TO 113
GO TO 5
113 CONTINUE
DO 553 II=1,N
553 XA1(II)=XO(II)
FA1=FO
GO TO 66
43 CONTINUE
IF(IPRINT)20,21,20
20 CONTINUE
WRITE(6,99)
99 FORMAT(IX,'RICERCA RIUSCITA DI UN PASSO ARBITRARIO DI DISCESA')
WRITE(6,94)(XA1(IB),IB=1,N)
WRITE(6,89)FA1
21 CONTINUE
66 CONTINUE
C MINIMIZZAZIONI LUNGO DIRL CON L=N-K+i...N
J=N-K
6 J=J+1

```

```

EPS2=EPS*EPS3
CALL SEARD(DIRN,IFMAX1,EPS2,XA1,N,FA1,XMU,SC,IFUN)
IF(IPRINT)22,23,22
22 CONTINUE
WRITE(6,93)
WRITE(6,94)(XA1(IB),IB=1,N)
WRITE(6,89) FA1
23 CONTINUE
IF(IFUN.GE.IFMAX) GO TO 1001
IF(J.EQ.N) GO TO 62
GO TO 6
62 CONTINUE
C CALCOLO DELLA NUOVA MATRICE DELLE DIREZIONI DI RICERCA
XMOD=0.0
DO 8 II=1,N
8 XMOD=XMOD+(XA1(II)-XA(II))**2
XMOD=DSQRT(XMOD)
DO 7 JJ=1,N
IF(JJ.LT.L) GO TO 7
IF(JJ.EQ.N) GO TO 71
DO 72 II=1,N
72 DIR(II,JJ)=DIR(II,JJ+1)
GO TO 7
71 DO 73 II=1,N
73 DIR(II,JJ)=XA1(II)-XA(II)
7 CONTINUE
DO 81 II=1,N
XA(II)=XA1(II)
81 DIR(II,N)=DIR(II,N)/XMOD
FA=FA1
147 IF(K.EQ.(N-1)) GO TO 1
GO TO 2
1001 WRITE(6,104)
104 FORMAT(1H1,14HIFMAX EXCEEDED)
GO TO 1002
1000 WRITE(6,100)IFUN,I,K
100 FORMAT(//,1X,19HOPTIMUM FOUND AFTER,IS,15HFUNCTION CALLS,,,
1I5,7HCYCLES,,I5,11HSIMPLE IER,)
1002 CONTINUE
WRITE(6,101)
101 FORMAT(1X,2HX=)
WRITE(6,102) (XA1(I),I=1,N)
102 FORMAT(4(2X,D14.7))
WRITE(6,103) FA
103 FORMAT(1X,24HMINIMUM FUNCTION VALUE =,D14.7)
RETURN
END

```

```

SUBROUTINE SEARD(D,IFMAX1,EPS2,X0,N,F0,MU,X,IFUN)
C QUESTO SOTTOPROGRAMMA ESEGUE LA RICERCA MONODIMENSIONALE
C MU RAFFRESENTA IL PASSO INIZIALE PER LA RICERCA MONODIMENSIONALE
C EPS2 E' LA PRECISIONE NELLA RICERCA MONODIMENSIONALE
DIMENSION X0(50),D(50),X1(50)
DOUBLE PRECISION D,EPS2,X0,F0,MU,X,F,X1,DV,FV,DB,FB
DOUBLE PRECISION FC,DC,XSTEP,XINC,DA,FA
ITEST=3
MU=DMAX1(DABS(X),1.5*EPS2)
XSTEP=DSIGN(MU,X)
X=0.0
F=F0
C CALCOLO DEI PUNTI DA INTERPOLARE
51 GO TO 2000
2100 GO TO(1,2,335,336),ITEST
1 DO 70 I=1,N
70 X1(I)=X0(I)+X*D(I)
CALL CALFUD(X1,N,F,IFUN)
GO TO 51
2 CONTINUE.
C CALCOLO DEL MINIMO MONODIMENSIONALE
DO 377 I=1,N
377 X1(I)=X0(I)+DV*D(I)
CALL CALFUD(X1,N,FV,IFUN)
IF(F-FV)50,50,59
59 F=FV
X=DV
50 IF(F.LT.F0) GO TO 60

```

```

F=FO
X=0.0
123 FORMAT (1X,I4)
GO TO 2200
60 DO 30 I=1,N
30 XG(I)=XO(I)+X*D(I)
FO=F
GO TO 2200
335 CONTINUE
GO TO 50
336 WRITE(6,122)
122 FORMAT(1H1,14HIFMAX EXCEEDED)
GO TO 50
2000 CONTINUE
GO TO(91,222,222),ITEST
222 IS=6-ITEST
ITEST=1
IINC=1
XINC=XSTEP+XSTEP
MC=IS-3
IF(MC) 4,4,15
3 MC=MC+i
IF(IFMAX1-MC) 12,15,15
C C CASO IN CUI E' STATO RAGGIUNTO IL MASSIMO NUMERO DI VALUTAZIONE
C DI FUNZIONE
12 ITEST=4
43 X=DB
F=FB
IF(FB-FC) 15,15,44
44 X=DC
F=FC
15 GO TO 2100
9i GO TO (5,6,7,8),IS
8 IS=3
4 DC=X
FC=F
X=X+XSTEP
GO TO 3
C CONFRONTO TRA VALORE DELLA FUNZIONE NEL PUNTO INIZIALE E NEL
C PUNTO ATTUALE
7 IF(FC-F) 9,10,11
10 X=X+XINC
XINC=XINC+XINC
GO TO 3
9 DB=X
FB=F
XINC=-XINC
GO TO 13
11 DB=DC
FB=FC
DC=X
FC=F
13 X=DC+DC-DB
IS=2
GO TO 3
6 DA=DB
DB=DC
FA=FB
FB=FC
32 DC=X
FC=F
GO TO 14
5 IF(FB-FC) 16,17,17
17 IF(F-FA) 18,32,32
18 FA=FB
DA=DB
19 FB=F
DB=X
GO TO 14
16 IF(FA-FC) 21,21,20
20 XINC=FA
FA=FC
FC=XINC
XINC=DA
DA=DC
DC=XINC
21 XINC=DC
IF((DV-DB)*(DV-DC)) 32,22,22
22 IF(F-FA) 23,24,24
23 FC=FB
DC=DB
GO TO 19
24 FA=F
DA=X
14 IF(FB-FC) 25,25,29
25 IINC=2
XINC=DC

```

```
IF(FB-FC) 29,45,29
C CALCOLO DELL'ASCISSA DEL VERTICE DELLA PARABOLA INTERPOLANTE
29 DV=(FA-FB)/(DA-DB)-(FA-FC)/(DA-DC)
IF(DV*(DB-DC))33,33,37
37 DV=0.5*(DB+DC-(FB-FC)/DV)
C ESECUZIONE DEL CRITERIO DI ARRESTO CON PRECISIONE ASSOLUTA O RELATIVA
56 IF(DABS(DV-X)-DABS(EPS2))34,34,35
35 IF(DABS(DV-X)-DABS(DV*EPS2))34,34,36
34 ITEST=2
GO TO 43
36 IS=1
X=DV
IF((DA-DC)*(DC-DV))3,26,38
38 IS=2
GO TO (3,40),IINC
33 IS=2
GO TO (41,42),IINC
41 X=DC
GO TO 10
40 IF(DABS(XINC-X)-DABS(X-DC)) 42,42,3
42 X=0.5*(XINC+DC)
IF((XINC-X)*(X-DC)) 26,26,3
45 X=0.5*(DB+DC)
IF((DB-X)*(X-DC)) 26,26,3
26 ITEST=3
GO TO 43
2200 CONTINUE
RETURN
END
```

```
SUBROUTINE CALFUD(X,N,F,IFUN)
C QUESTO SOTTOPROGRAMMA CALCOLA LA FUNZIONE DA MINIMIZZARE NEL PUNTO
C ATTUALE
C X RAPPRESENTA IL PUNTO IN CUI VIENE CALCOLATA LA FUNZIONE
C N RAPPRESENTA LA DIMENSIONE DEL DOMINIO DELLA FUNZIONE DA MINIMIZZARE
C F RAPPRESENTA LA FUNZIONE OBIETTIVO
C IFUN RAPPRESENTA IL NUMERO DI VALUTAZIONI DI FUNZIONE ESEGUITE
DOUBLE PRECISION X(50),F
IFUN=IFUN+1
F=100.*(X(2)-X(1))*X(1))*(X(2)-X(1))*X(1))+(1-X(1))*(1-X(1))
1000 CONTINUE
RETURN
END
```

```
N = 2
IFMAX = 10000      XMU = 0.5000000D 00
EPS = 0.100000D-04    EPS1 = 0.100000D-04
EPS3= 0.100000D 03    EPS4 = 0.100000D 01
X=
-0.1200000D 01    0.1000000D 01
```

```
OPTIMUM FOUND AFTER 268FUNCTION CALLE, 12CYCLES, 1SIMPLE IER,
X=
0.1000002D 01    0.1000005D 01
MINIMUM FUNCTION VALUE = 0.2554003D-10
```

Table 3

NPROB	N	XZERO	CYC	ITER	IFUN	TEMP	F
1	4	1	8	3	500	8	0.6853185E-11
1	4	2	9	3	539	9	0.1694644E-10
1	4	3	16	3	992	12	0.4928680E-10
2	4	1	6	1	335	9	0.4614324E-10
2	4	2	6	3	325	9	0.1663981E-08
2	4	3	5	2	289	9	0.4886158E-04
3	4	1	4	1	200	8	0.1043268E-22
3	4	2	4	1	197	7	0.3698358E-22
3	4	3	2	3	158	7	0.9999406E-13
4	4	1	6	3	502	10	0.2911109E-04
4	4	2	13	3	943	14	0.2416260E-04
4	4	3	10	3	783	13	0.2552328E-04
5	4	1	4	1	243	7	0.0000000E 00
5	4	2	4	1	242	8	0.1776357E-13
5	4	3	5	1	280	9	0.1705303E-12
6	4	1	3	3	175	11	0.4571443E-10
6	4	2	4	1	209	11	0.1149114E-10
6	4	3	4	2	207	11	0.3028162E-03
7	4	1	1	1	46	6	0.2666667E 01
7	4	2	1	1	89	6	0.2666667E 01
7	4	3	1	1	68	7	0.2666667E 01
8	4	1	5	1	253	9	0.5435652E-12
8	4	2	4	2	204	8	0.4867218E-12
8	4	3	4	1	229	8	0.6373639E 00
9	4	1	3	2	137	15	0.5829702E-07
9	4	2	3	3	178	20	0.3902016E-08
9	4	3	4	1	206	20	0.1164722E-09
10	4	1	4	3	197	33	0.6958773E-01
10	4	2	4	2	193	32	0.6958733E-01
10	4	3	4	3	197	33	0.6958773E-01
11	4	1	3	3	190	11	0.9537200E-05
11	4	2	2	3	128	10	0.9547088E-05
11	4	3	3	2	239	13	0.9715007E-03
12	4	1	4	1	218	10	0.1008360E-11
12	4	2	4	1	210	11	0.5739853E-13
12	4	3	6	2	523	15	0.1447365E-09

NPROB	N	XZERO	CYC	ITER	IFUN	TEMP	F
1	10	1	31	9	7879	97	0.1547769E-01
1	10	2	8	1	2420	33	0.1331713E 00
1	10	3	21	8	5610	131	0.1971989E 00
2	8	1	10	7	1814	28	0.3519635E-08
2	8	2	9	7	1597	25	0.2412440E-05
2	8	3	12	5	2665	38	0.1382726E 01
3	10	1	2	6	1286	22	0.1671677E-16
3	10	2	7	4	1887	33	0.2008595E-18
3	10	3	3	9	1323	23	0.8578724E-18
4	10	1	7	7	2830	47	0.7836072E-04
4	10	2	7	9	2347	42	0.8022473E-04
4	10	3	1	9	1073	21	0.1569622E-02
5	10	1	14	1	3538	68	0.5594076E-09
5	10	2	12	5	2991	59	0.5836753E-09
5	10	3	19	7	4790	89	0.3711815E-08
6	10	1	3	9	722	43	0.3328136E-05
6	10	2	6	5	1464	78	0.3849585E-07
6	10	3	4	7	1021	57	0.3792897E-07
7	10	1	1	1	129	9	0.4142857E 01
7	10	2	1	2	257	12	0.4142857E 01
7	10	3	1	2	138	10	0.4142858E 01
8	10	1	5	3	1171	29	0.8728691E-02
8	10	2	9	8	2196	49	0.3500761E-02
8	10	3	20	2	515	102	0.9329068E 01
9	10	1	3	9	1110	520	0.9229598E-06
9	10	2	3	1	773	364	0.1649823E-08
9	10	3	5	1	1276	598	0.7796643E-09
10	10	1	3	2	696	237	0.7461312E-04
10	10	2	3	8	776	263	0.6785664E-04
10	10	3	3	2	696	237	0.7461312E-04
11	10	1	5	2	2033	159	0.2944994E-03
11	10	2	4	9	1581	118	0.2945766E-03
11	10	3	3	3	1634	130	0.2979358E-03
12	10	1	5	8	1209	84	0.4784756E-01
12	10	2	5	3	1151	81	0.4331340E-01
12	10	3	7	9	2984	195	0.2152653E-01

Table 4

NPROB	N	XZERO	CYC	ITER	IFUN	TEMP	F
1	4	1	8	1	438	18	0.1885337D-14
1	4	2	7	3	406	18	0.7893525D-11
1	4	3	15	2	810	30	0.5298247D-10
2	4	1	7	3	390	19	0.4175356D-13
2	4	2	8	3	470	22	0.2444547D-13
2	4	3	5	3	300	16	0.6097524D-04
3	4	1	4	1	199	11	0.9424900D-23
3	4	2	4	1	199	12	0.4550525D-22
3	4	3	3	1	143	11	0.3774113D-14
4	4	1	6	3	375	20	0.2909931D-04
4	4	2	6	3	375	20	0.2909966D-04
4	4	3	11	3	776	34	0.2509131D-04
5	4	1	4	1	193	14	0.2232696D-21
5	4	2	4	1	193	14	0.4521384D-21
5	4	3	4	1	211	15	0.1526355D-14
6	4	1	4	1	205	52	0.2328290D-15
6	4	2	4	1	205	51	0.3531229D-15
6	4	3	4	3	219	54	0.3028241D-03
7	4	1	1	1	29	7	0.2666667D 01
7	4	2	1	1	50	8	0.2666667D 01
7	4	3	1	1	33	8	0.2666667D 01
8	4	1	4	1	175	12	0.3627790D-11
8	4	2	4	1	194	13	0.4590915D-11
8	4	3	4	1	197	14	0.6373640D 00
9	4	1	3	1	128	105	0.6961723D-08
9	4	2	3	1	126	104	0.4653792D-07
9	4	3	4	1	180	146	0.3501550D-12
10	4	1	4	3	227	156	0.6958772D-01
10	4	2	4	3	227	160	0.6958772D-01
10	4	3	4	3	227	156	0.6958772D-01
11	4	1	2	3	87	27	0.9720844D-05
11	4	2	2	3	106	41	0.9499948D-05
11	4	3	3	2	152	44	0.9714704D-05
12	4	1	4	1	191	21	0.6416760D-13
12	4	2	4	1	188	28	0.2190830D-13
12	4	3	7	1	449	39	0.1317098D-12

NPROB	N	XZERO	CYC	ITER	IFUN	TEMP	F
1	10	1	14	7	3837	222	0.1749111D 00
1	10	2	7	4	2435	153	0.3328696D-01
1	10	3	10	7	2813	163	0.2777195D 00
2	8	1	9	7	1693	105	0.1821409D-08
2	8	2	10	7	1887	118	0.3475085D-07
2	8	3	19	7	3558	234	0.9311145D-10
3	10	1	3	2	696	45	0.1536921D-20
3	10	2	3	2	696	45	0.1546087D-20
3	10	3	2	5	718	41	0.3342667D-13
4	10	1	10	9	3142	239	0.8964973D-04
4	10	2	8	7	2480	190	0.7415362D-04
4	10	3	6	7	1858	144	0.1021991D-03
4	10	1	5	1	1245	109	0.1364837D-13
5	10	2	5	8	1420	111	0.8588377D-10
5	10	3	6	3	1633	124	0.7062060D-10
6	10	1	5	8	1340	723	0.4473892D-06
6	10	2	5	6	1282	693	0.3214896D-10
6	10	3	4	8	1092	591	0.7681483D-10
7	10	1	1	1	124	25	0.4142857D 01
7	10	2	1	1	217	39	0.4142857D 01
7	10	3	1	1	211	36	0.4142857D 01
8	10	1	9	6	2278	180	0.1773174D-09
8	10	2	10	1	2451	194	0.8389859D-12
8	10	3	11	2	3179	252	0.3898880D 01
9	10	1	3	1	570	3241	0.1106292D-16
9	10	2	2	1	298	1697	0.1166062D-04
9	10	3	4	9	1072	6099	0.4612646D-06
10	10	1	2	9	552	679	0.9520944D-04
10	10	2	2	9	555	951	0.7608388D-04
10	10	3	2	9	552	679	0.9520944D-04
11	10	1	10	9	3447	2694	0.2945644D-03
11	10	2	8	8	2666	1863	0.2943835D-03
11	10	3	9	8	2974	2052	0.2952027D-03
12	10	1	9	1	2169	602	0.4772714D-02
12	10	2	5	8	1294	366	0.4777713D-02
12	10	3	12	5	4379	1186	0.6718247D-01

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