# WHEN MAY TWO SYSTEMS OF ORTHONORMAL FUNCTIONS BE INTERCHANGED IN VECTOR-VALUED ORTHOGONAL SUMS?

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**Abstract.** Given a finite orthonormal sequence  $\Phi_n = (\varphi_1, \dots, \varphi_n)$  in some  $L_2(\mu)$  and vectors  $x_1, \dots, x_n$  in some Banach space X we are interested in the norm of the sums  $\sum_{j=1}^n \varphi_j(t)x_j$  in  $L_2^X(\mu)$ . A construction in [1] suggests that the system  $\Phi_n$  may be replaced by the set  $\Pi_n = (\pi_1, \dots, \pi_n)$  of coordinate functions  $\pi_j(\sigma_1, \dots, \sigma_n) = \sigma_j$  on  $\mathbb{S}^{n-1}$  viewed as an orthonormal system with respect to a suitable measure  $\lambda$  on  $\mathbb{S}^{n-1}$ . We show by a convolutional argument that after symmetrization the measure  $\lambda$  is uniquely determined. We also discuss related questions.

#### 1. INTRODUCTION

Many features in Banach space theory such as type and cotype may be stated in terms of suitable orthogonal vector-valued sums and inequalities between their  $L_2$ -norms (cf. [2], [1]). In our setting we focus on sums

$$\sum_{j=1}^{n} \varphi_{j} x_{j}$$

where the  $x_1, \ldots, x_n$  are vectors in some Banach space X and the n-tupel of functions  $\Phi_n = (\varphi_1, \ldots, \varphi_n)$  is an orthonormal system in some Hilbert space  $L_2(\mu)$ . We think of n and  $\Phi_n$  as fixed for a moment. If  $\Psi_n = (\psi_1, \ldots, \psi_n)$  is another orthonormal system in some  $L_2(\lambda)$  there seems to exist no general criterion whether we have for instance

$$\left(\int \left\|\sum_{j=1}^{n} \varphi_{j}(t) x_{j}\right\|^{2} \mu(dt)\right)^{1/2} \leq C \left(\int \left\|\sum_{j=1}^{n} \psi_{j}(s) x_{j}\right\|^{2} \lambda(ds)\right)^{1/2}$$
(1)

regardless of the Banach spaces X and the vectors  $x_1, \ldots, x_n$  in X with some given constant  $C \ge 1$ . Not so, if in (1) we insist on equality and C = 1. We shall see that in the affirmative case the two systems in question will share the same *projective distribution*.

Before engaging in the definition, let us first fix the notation.

The scalar field will be  $\mathbb{C}$ . With obvious modifications the results will apply to the real case simultaneously.

We shall write  $||x||_2$  for the euclidean norm of a vector  $x = (\xi_1, \dots, \xi_n)$  in  $\ell_2^n$ . Moreover,  $x^* : \ell_2^n \to \mathbb{C}$  will be the corresponding functional and  $x^* \otimes x$  the  $n \times n$  matrix with entries  $\overline{\xi_i} \xi_k$ . The unit vectors are denoted by  $e_1, \dots, e_n$ .

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 $\mathbb{S}^{n-1}$  is the set of all vectors in  $\mathbb{C}^n$  of euclidean norm 1. The natural mappings

$$\pi_j: \mathbb{S}^{n-1} \to \mathbb{C}, \qquad s = (\sigma_1, \dots, \sigma_n) \mapsto \sigma_j \qquad (j = 1, \dots, n)$$

will play a special part in our theory. We use the symbol  $\Pi_n = (\pi_1, \dots, \pi_n)$  for this system of functions.

 $C(\mathbb{S}^{n-1})$  is the Banach space of all continuous complex functions on  $\mathbb{S}^{n-1}$ . By the Riesz representation theorem its dual is  $M(\mathbb{S}^{n-1})$ , the space of all complex measures on  $\mathbb{S}^{n-1}$ . The duality is given by

$$(f,\beta)\mapsto \int_{\mathbb{S}^{n-1}}g(s)\beta(ds).$$

On the torus  $\mathbb{T}$ , the group of complex numbers of modulus 1, we denote the Haar measure by  $m_{\mathbb{T}}$ . Similarly, on the group  $\mathbf{U}_n$  of unitary  $n \times n$  matrices we denote the Haar measure by  $m_{\mathbf{U}_n}$ . The unit matrix is  $I_n$ .

For our purposes it will be convenient not to distinguish between an *n*-tupel of functions  $\Phi_n = (\varphi_1, \dots, \varphi_n)$  in some  $L_2(\mu)$  and the  $\Sigma$ -measurable map given by

$$\Phi_n: \Omega \to \mathbb{C}^n$$
,  $t \mapsto \Phi_n(t) = \sum_{j=1}^n \varphi_j(t)e_j$ .

It is important to mention that  $\Phi_n = (\varphi_1, \dots, \varphi_n)$  is an orthonormal system if and only if

$$\int \Phi_n(t) * \otimes \Phi_n(t) \mu(dt) = I_n.$$
 (2)

Note that (2) is merely shorthand for

$$\int \overline{\varphi_j(t)} \varphi_k(t) \mu(dt) = \delta_{jk} \qquad (j, k = 1, \dots, n).$$

Note that any measure  $\mu$  that fulfills these  $n^2$  conditions will turn a give map  $\Omega_n : \Sigma \to \mathbb{C}^n$  into an orthonormal system. When it is advisable to be more careful about the underlying measure we rather use the symbol  $[\Phi_n, \mu]$  in order to indicate the dependence.

If there are given vectors  $x_1, \ldots, x_n$  in some Banach space X we define

$$U: \ell_2^n \to X, e_j \mapsto x_j \quad (j = 1, \ldots, n).$$

Let us denote the Banach space of square Bochner- $\mu$ -integrable X-valued functions by  $L_2^X(\mu)$ . Then  $U\Phi_n: t \mapsto U(\Phi_n(t))$  is a member of  $L_2^X$  and we have

$$\left(\int \|\sum_{j=1}^n \varphi_j(t) x_j\|^2 \mu(dt)\right)^{1/2} = \|U\Phi_n\|_{L_2^x(\mu)}.$$

## 2. THE PROJECTIVE DISTRIBUTION

Let us fix n and an orthonormal system  $\Phi_n \subset L_2(\mu)$  for the time being. Given  $U: \ell_2^n \to X$  we may certainly write

$$\|U\Phi_{n}\|_{L_{2}^{X}9\mu}) = \left(\int_{\{\Phi_{n}\neq0\}} \|U\Phi_{n}(t)\|^{2} \mu(dt)\right)^{1/2}$$

$$= \left(\int_{\{\Phi_{n}\neq0\}} \left\|\frac{U\Phi_{n}(t)}{\|\Phi_{n}(t)\|_{2}}\right\|^{2} \|\Phi_{n}(t)\|_{2}^{2} \mu(dt)\right)^{1/2}$$

$$= \left(\int_{\mathbb{T}} \int_{\{\Phi_{n}\neq0\}} \left\|U\left(\frac{\sigma\Phi_{n}(t)}{\|\Phi_{n}(t)\|_{2}}\right)\right\|_{X}^{2} \|\Phi_{n}(t)\|_{2}^{2} \mu(dt)m_{\mathbb{T}}(d\sigma)\right)^{1/2}.$$
(3)

This observation forces our way.

**Definition 1.** Let  $\Phi_n \subset L_2(\mu)$  be an orthonormal system. The measure  $\lambda = \lambda (\Phi_n, \mu)$  on  $\mathbb{S}^{n-1}$  given by

$$\int f(s)\lambda(ds) = \int_{\mathbb{T}} \int_{\{\Phi_n \neq 0\}} f\left(\frac{\sigma\Phi_n(t)}{\|\Phi_n(t)\|_2}\right) \|\Phi_n(t)\|_2^2 \mu(dt) m_{\mathbb{T}}(d\sigma) \qquad (f \in C(\mathbb{S}^{n-1}))$$
(4)

is called the projective distribution of  $\Phi_n$  (with respect to  $\mu$ ).

A note on the terminology is in order: Averaging over  $\mathbb{T}$  will force  $\lambda$  to be  $\mathbb{T}$ -invariant. Thus,  $\lambda$  may be looked upon as a measure on the projective plane  $\mathbb{C}_*^n / \mathbb{C}_* \equiv \mathbb{S}^{n-1} / \mathbb{T}$ . Indeed, whithout symmetrization and with a different normalization this is exactly the construction in [1], Lemma 3.7 (1), p. 428.

**Theorem 2.** Let  $\Phi_n \subseteq L_2(\mu)$  be an orthonormal system. Then its projective distribution  $\lambda$  is uniquely determined by the following properties:

- (i) The system of projections  $\Pi_n = (\pi_1, \dots, \pi_n)$  is orthonormal with respect to  $\lambda$ . In particular  $\lambda$  has total mass n.
- (ii)  $\lambda$  is  $\mathbb{T}$ -invariant
- (iii) For all Banach space X und for all  $U: \ell_2^n \to X$  we have

$$||U\Pi_n||_{L_2^X(\lambda)} = ||U\Phi_n||_{L_2^X(\mu)}.$$

**Proof.** Clearly,  $\lambda$  is a positive measure on  $\mathbb{S}^{n-1}$ . Let us start by verifying (i) to (iii).

(i): For fixed  $j, l \in \{1, ..., n\}$  define a continuous function g on  $\mathbb{S}^{n-1}$  by  $g(s) = \overline{\pi_j(s)} \pi_l(s)$   $(s \in \mathbb{S}^{n-1})$ . Then,

$$\int_{\mathbb{S}^{n-1}} \overline{\pi_{j}(s)} \pi_{l}(s) \lambda(ds) = \int \int \frac{\overline{\sigma \varphi_{j}(t)}}{\|\Phi_{n}(t)\|} \frac{\sigma \varphi_{l}(t)}{\|\Phi_{n}(t)\|} \|\Phi_{n}(t)\|^{2} \mu(dt) m_{\mathbb{T}}(d\sigma)$$

$$= \int \overline{\varphi_{j}(t)} \varphi_{j}(t) \mu(dt)$$

$$= \delta_{jl}.$$

Moreover, if we put  $g(s) = \|\Pi_n(s)\|_2^2 = \sum_{j=1}^n |\sigma_j|^2 \equiv 1 \ (s \in \mathbb{S}^{n-1})$  we get

$$\lambda(\mathbb{S}^{n-1}) = \int \|\Pi_n(s)\|_2^2 \lambda(ds) = \int \int \|\zeta \Phi_n(t)\|_2^2 \mu(dt) m_{\mathbb{T}}(d\zeta) = \sum_{j=1}^n \int |\varphi_j(t)|^2 \mu(dt) = n.$$

(ii): For continuous functions g on  $\mathbb{S}^{n-1}$  and complex numbers  $\tau$  of modulus 1 we have

$$\int f(\tau s)\lambda(ds) = \int_{\mathbb{T}} \int_{\Phi_n \neq 0} f\left(\frac{\tau \sigma \Phi_n(t)}{\|\Phi_n(t)\|_2}\right) \|\Phi_n(t)\|_2^2 \mu(dt) m_{\mathbb{T}}(d\sigma) 
= \int_{\mathbb{T}} \int_{\Phi_n \neq 0} f\left(\frac{\sigma \Phi_n(t)}{\|\Phi_n(t)\|_2}\right) \|\Phi_n(t)\|_2^2 \mu(dt) m_{\mathbb{T}}(d\sigma) = \int f(s)\lambda(ds).$$

(iii): This is the very definition of  $\lambda$ . Given  $U: \ell_2^n \to X$ , define  $g \in C(\mathbb{S}^{n-1})$  by  $g(s) = ||U\Pi_n(s)||^2$   $(s \in \mathbb{S}^{n-1})$ . We get

$$||U\Pi_n||_{L_2^X(\lambda)} = \left(\int ||U\Pi_n(s)||^2 \lambda(ds)\right)^{1/2}$$

$$= \left(\int ||U\Phi_n(t)||^2 \mu(dt)\right)^{1/2} = ||U\Phi_n||_{L_2^X(\mu)}.$$

As for the reverse, we shall apply a density argument.

We will construct a sequence  $\{\|\cdot\|_{(k)}\}_{k=1}^{\infty}$  of norms on  $\mathbb{C}^n$  such that any continuous and  $\mathbb{T}$ -invariant function g may be uniformly approximated by linear combinations of the form

$$s \mapsto \sum_{j=1}^{N} a_j ||V_j \Pi_n(s)||_{(k)}^2,$$

where  $a_j \in \mathbb{C}$  and  $V_j \in \mathbf{U}_n$ .

Indeed, if we are given two measures  $\lambda$  and  $\tilde{\lambda}$  on  $\mathbb{S}^{n-1}$  with the property that

$$\int ||U\Pi_n(s)||_X^2 \lambda(ds) = \int ||U\Phi_n(t)||_X^2 \mu(dt) = \int ||U\Pi_n(s)||_X^2 \tilde{\lambda}(ds)$$

however we choose X and  $U: \ell_2^n \to X$  then we may conclude by approximation that

$$\int g(s)\lambda(ds) = \int g(s)\tilde{\lambda}(ds)$$

for every  $\mathbb{T}$ -invariant  $g \in C(\mathbb{S}^{n-1})$ . Furthermore, if  $f \in C(\mathbb{S}^{n-1})$  then

$$g(s) = \int f(\tau s) m_{\mathbb{T}}(d\tau) \qquad (s \in \mathbb{S}^{n-1})$$

is  $\mathbb{T}$ -invariant and by virtue of (ii)

$$\int f(s)\lambda(ds) = \int \int f(\tau s)\lambda(ds)m_{\mathbb{T}}(d\tau) = \int g(s)\lambda(ds) = \int g(s)\tilde{\lambda}(ds).$$

The same holds if we interchange  $\tilde{\lambda}$  and  $\lambda$ , hence

$$\int f(s)\lambda(ds) = \int f(s)\tilde{\lambda}(ds).$$

Appealing to Riesz representation theorem shows that  $\lambda = \tilde{\lambda}$  and thus our issue is settled. We proceed in four steps.

Step 1: Determine  $r_k > 0 (k = 1, 2, ...)$  such that

$$|\sigma_1| > r_k$$
 if  $||s - \tau e_1||_2 < 2^{-1}$  for some  $\tau \in \mathbb{T}$   $(s = (\sigma_1, \dots, \sigma_n) \in \mathbb{S}^{n-1})$ 

Define norms

$$\|\cdot\|_{(k)}: \mathbb{C}^n \longrightarrow \mathbb{R}_+$$

$$x = (\xi_1, \dots, \xi_n) \longmapsto \max\left\{\frac{|\xi_1|}{r_k}, \|x\|_2\right\}.$$

Recall that  $\|\cdot\|_2$  is the euclidean norm.  $\|\cdot\|_{(k)}$  is certainly a norm again and by construction

$$||s||_{(k)} = 1$$
 if  $||s - \tau e_1||_2 \ge 2^{-k}$  for all  $\tau \in \mathbb{T}$   $(s \in \mathbb{S}^{n-1}, k = 1, 2, ...)$  (5)

Step 2: For the following we denote the rotational invariant probability measure on  $\mathbb{S}^{n-1}$  by m. We continue by defining a sequence  $(h_k)_{k=1}^{\infty}$  of continuous non-negative functions on  $\mathbb{S}^{n-1}$  by

$$h_k(s) = \frac{\|s\|_{(k)}^2 - 1}{\int \|y\|_{(k)}^2 m(dy) - 1} \quad (s \in \mathbb{S}^{n-1})$$

Note that the denominator does not vanish. Obviously, all  $h_k$  are continuous. They have the following usefull properties:

$$\int h_k(s)m(ds) = 1 \tag{6}$$

$$h_k(s) = 0 \quad \text{if} \quad ||s - \tau e_1||_2 \ge 2^{-k} \quad \text{for all} \quad \tau \in \mathbb{T}.$$
 (7)

Every 
$$h_k$$
 is a linear combination of  $\|\cdot\|_{(k)}^2$  and  $\|\cdot\|^2$ . (8)

Step 3: Now, let g be a  $\mathbb{T}$ -invariant function on  $\mathbb{S}^{n-1}$ . Define the "convolution"

$$g_k(s) = \int g(V^{-1}e_1)h_k(Vs)m_{\mathbf{U}_n}(dV) \quad (s \in \mathbb{S}^{n-1}).$$

Claim:

$$g = \lim_{k \to \infty} g_k \quad \text{in} \quad C(\mathbb{S}^{n-1}). \tag{9}$$

By virtue of  $\mathbb{T}$ -invariance and uniform continuity, given  $\varepsilon > 0$  we find  $k \in \mathbb{N}$ , such that for any two points s and y in  $\S^{n-1}$ 

$$||s - y||_2 < 2^{-k}$$
 implies  $|g(s) - g(y)| < \varepsilon$ .

If for this particular k the term  $h_k(Vs)$  is greater than 0 then (7) guaranties the existence of some  $\tau \in \mathbb{T}$  such that  $||s - \tau V^{-1} e_1||_2 = ||Vs - \tau e_1||_2 < 2^{-k}$ . The function g being  $\mathbb{T}$ -invariant we conclude  $g(\zeta V^{-1}e_1) = g(V^{-1}e_1)$  and  $|g(s) - g(V^{-1}e_1)| < \varepsilon$ . Consequently, we have the following inequalities

$$|g(s) - g_k(s)| \leq \int |g(s) - g(V^{-1}e_1)| h_k(Vs) m_{\mathbf{U}_n}(dV)$$

$$\leq \varepsilon \int h_k(Ve_1) m_{\mathbf{U}_n}(dV)$$

$$= \varepsilon \int h_k(s) m(ds) = \varepsilon.$$

This proves claim (9) since everything applies uniformly to all  $s \in \mathbb{S}^{n-1}$ .

Step 4: The  $g_k$  are now going to be approximated by suitable linear combinations of squares of norms. Towards this end we take some sequence  $\mathcal{F}_m$  ( $m \in \mathbb{N}$ ) of measurable partitions of  $\mathbf{U}_n$ , say of cardinality m and enumerated as follows  $\mathcal{F}_m = (F_{1m}, \dots, F_{mm})$ . We may require  $\mathcal{F}_m$  to fulfill

$$finess(\mathcal{F}_m) \stackrel{\text{def}}{=} \max_{j=1,\dots,m} \sup_{V,W \in F_{jm}} \|V - W\|_{\mathcal{L}(\ell_2^n,\ell_2^n)} \to 0 \quad (m \to \infty)$$

$$\tag{10}$$

Choose any  $V_{jm} \in F_{jm}$  and let

$$g_{km}(s) = \sum_{j=1}^{m} m_{\mathbf{U}_n}(F_{jm})g(V_{jm}^{-1}e_1)h_k(V_{jm}s) \qquad (s \in \mathbb{S}^{n-1}).$$

Claim: For all k we have:

$$g_k = \lim_{m \to \infty} g_{km} \quad \text{in} \quad C(\mathbb{S}^{n-1}). \tag{11}$$

Fix  $k \in \mathbb{N}$  and  $\varepsilon > 0$ . Due to the uniform continuity of g and  $h_k$  we may choose  $\delta > 0$  in such a way that for any  $y_1, y_2, s_1, s_2 \in \mathbb{S}^{n-1}$  with  $||y_1 - s_1|| < \delta$  and  $||y_2 - s_2|| < \delta$  we may conclude

$$|g(y_1)h_k(s_1)-g(y_2)h_k(s_2)|<\varepsilon.$$

Now, let  $m_0$  be sufficiently large to guarantee that  $finess(\mathcal{F}_m)$  will not exceed  $\delta$  for all  $m \geq m_0$ . Then we find uniformly in  $s \in \mathbb{S}^{n-1}$ 

$$|g_{km}(s) - g_{k}(s)| \leq \sum_{j=1}^{m} \int_{A_{jm}} |g(V^{-1}e_{1})h_{k}(Ve_{1}) - g(V_{jm}^{-1}e_{1})h_{k}(V_{jm}e_{1})|m_{\mathbf{U}_{n}}(dV)$$

$$\leq \varepsilon \sum_{j=1}^{m} m_{\mathbf{U}_{n}}(A_{jm} = \varepsilon.$$

This proves claim (11). Recall claim (9), and we are done.

Q.E.D.

#### 3. ROTATIONAL INVARIANCE

We are going to point out the special role of rotational invariant orthonormal systems. In the real case we consider an *n*-dimensional Gaussian vector  $G_n = (g_1, \ldots, g_n)$ , i.e. the  $g_j$  are i.i.d. with distribution

$$\mathbb{P}\{g_j \in F\} = \frac{1}{\sqrt{2\pi}} \int_F e^{-t^2/2} dt \qquad (F \text{ Borel subset of } \mathbb{R}^n).$$

In the complex case the *n*-dimensional Gaussian vector  $\mathcal{G}_n = (g_1, \dots, g_n)$ , can be obtained by setting

$$g_j = \frac{1}{\sqrt{2}}\tilde{g}_{2j-1} + \frac{i}{\sqrt{2}}\tilde{g}_{2j} \qquad (j = 1, \dots, n)$$

provided  $(\tilde{g}_1, \ldots, \tilde{g}_{2n})$  is a 2n-dimensional real Gaussian vector (cf. [4] S12).

It is important to note that if  $V \in \mathbf{U}_n$  then the distributions of  $V\mathcal{G}_n$  and  $\mathcal{G}_n$  are the same. This is what we call *rotational invariance*.

**Definition 3.** An orthonormal system  $\Phi_n \in L_2(\mu)$  is called rotational invariant, provided

$$\mu\{V\Phi_n \in F\} = \mu\{\Phi_n \in F\} \qquad (V \in \mathbf{U}_n; F \quad Borel \ subset \ of \ \mathbb{C}^n). \tag{12}$$

Recall that we agreed on not distinguishing between the system  $\Phi_n$  and the induced  $\mathbb{C}^n$ -valued measurable map.

Taking into account that if  $\Phi_n$  is rotational invariant then its projective distribution is rotational invariant, too, and that there is only one rotational invariant measure on  $\mathbb{S}^{n-1}$  with total mass n, the following remark is obvious.

**Remark 4.** Let  $\omega_n$  be the (unique) rotational invariant measure on  $\mathbb{S}^{n-1}$  with total mass n. Suppose  $\Phi_n \in L_2(\mu)$  is rotational invariant then its projective distribution equals  $\omega_n$ .

The study of the projective distribution  $\lambda$  rather than that of the systems  $\Phi_n \subset L_2(\mu)$  in their own right was triggered off by investigating the behaviour of a certain generalization of the absolutely-2-summing ideal norm (cf. [3]).

If  $T: X \to Y$  is a bounded linear map, we define  $\pi(T|\Phi_n)$  to be the smallest constant C such that

$$||TU\Phi_n||_{L_2^{\gamma}(\mu)} \le C||U|| \quad \text{for} \quad U: \ell_2^n \to X.$$

$$\tag{13}$$

We consider two special cases.

(i) If the orthonormal system  $\chi_n = (\chi_1, \dots, \chi_n)$  is given by the indicator functions  $\chi_j = \mathbf{1}_{[j-1,j)} \in L_2(\mathbb{R})$  and if U is given by  $Ue_j = x_j$   $(j = 1, \dots, n)$  then the left hand side in (13) computes as

$$\left(\sum_{j=1}^{n} \|Tx_j\|^2\right)^{1/2}$$

labelled *strong*  $\ell_2$ -*sum* of the vector tupel  $(Tx_1, \ldots, Tx_n)$ . The right hand side in (13) computes as

$$\sup \left\{ \left( \sum_{j=1}^{n} |\langle x_j, x' \rangle|^2 \right)^{1/2} : x' \in X', ||x'|| \le 1 \right\},\,$$

known as the *weak*  $\ell_2$ -sum of the vector tupel  $(x_1, \ldots, x_n)$ . Accordingly,  $\pi(T|\chi_n)$  coincides with the absolutely-2-summing norm computed with respect to n vectors. (cf. [4] SS18, 23-26, [3]).

(ii) If the orthonormal system is  $\mathcal{G}_n = (g_1, \dots, g_n)$ , consisting of n independent Gaussian variables over some probability space  $(\Omega, \Sigma, \mathbb{P})$ , then  $\pi(T|\mathcal{G}_n)$  coincides with the  $\gamma$ -summing norm computed with respect to n vectors. (cf. [4] SS12, 23-26, [3]).

In turns out that among all ideal norms built according to the above procedure, there is one which has minimal value simultaneously for all  $T \in \mathcal{L}$ . We formulate a somewhat more general lemma.

**Lemma 5.** Let  $\Phi_n \subset L_2(\mu)$  and  $\tilde{\Phi}_n \subset L_2(\tilde{\mu})$  be two orthonormal systems with projective distribution  $\lambda$  and  $\tilde{\lambda}$ , respectively. Assume, there is some probability measure  $\mathbb{P}$  on  $\mathbf{U}_n$  such that

$$\int_{\mathbb{S}^{n-1}} g(x)\tilde{\lambda}(dx) = \int_{\mathbf{U}_n} \int_{\mathbb{S}^{n-1}} g(Vx)\lambda(dx)\mathbb{P}(dV) \qquad \left(g \in C(\mathbb{S}^{n-1})\right). \tag{14}$$

Then

$$\pi(T|\tilde{\Phi}_n) \leq \pi(T|\Phi_n) \quad (T \in \mathcal{L}).$$

**Proof.** Given operators  $\ell_2^n \stackrel{U}{\rightharpoonup} X \stackrel{T}{\rightharpoonup} Y$  we find

$$||TUV\Pi_n||_{L_2^Y(\lambda)} = ||TUV\Phi_n||_{L_2^Y(\mu)} \le c||UV|| = c||U|| \qquad (V \in \mathbf{U}_n),$$

where  $c = \pi(T|\Phi_n)$ . Square, integrate against  $\mathbb{P}(dV)$ , and take the square root, then

$$||TU\tilde{\Phi}_n||_{L_2^{\gamma}(\tilde{\mu})} = ||TU\Pi_n||_{L_2^{\gamma}(\tilde{\lambda})} = \left(\int ||TUV\Pi_n||_{L_2^{\gamma}(\lambda)}^2 \mathbb{P}(dV)\right)^{1/2} \leq c||U||.$$

As  $U: \ell_2^n \to X$  was arbitrary we have  $\pi(T|\tilde{\Phi}_n) \leq c$ .

Q.E.D.

Note that the situation in (14) can be arranged in a simple manner: Given an orthonormal system  $\Phi_n$  and some probability measure  $\mathbb{P}$  on  $\mathbf{U}_n$ , we may *define* 

$$\tilde{\Phi}_n : \Omega \times \mathbf{U}_n \longrightarrow \mathbb{C}^n,$$

$$(t, V) \mapsto V\Phi_n(t)$$

It is immediate to see, that if  $\tilde{\lambda}$  is the projective distribution of this particular  $\tilde{\Phi}_n$  indeed (14) holds with the same  $\mathbb{P}$ . Moreover this construction always yields an orthonormal system,

since

$$\int_{\mathbb{S}^{n-1}} \tilde{\Phi}_n(t)^* \otimes \tilde{\Phi}_n(t) \tilde{\mu}(dt) = \int_{\mathbf{U}_n} V\left(\int_{\mathbb{S}^{n-1}} \Phi_n(t)^* \otimes \Phi_n(t) \mu(dt)\right) V^* \mathbb{P}(dV)$$

$$= \int_{\mathbf{U}_n} V I_n V^* \mathbb{P}(dV)$$

$$= \int_{\mathbf{U}_n} I_n \mathbb{P}(dV) = I_n.$$

The case in consideration is merely specialized to the situation where  $\Phi_n = \Pi_n$ . The author has the strong feeling that a converse of the above lemma holds true.

**Conjecture:** Given two orthonormal system  $\Phi_n$  and  $\tilde{\Phi}_n$  such that

$$\pi(T|\tilde{\Phi}_n) \le \pi(T|\Phi_n) \qquad (T \in \mathcal{L}),$$

then necessarily there is a probability  $\mathbb{P}$  measure on  $\mathbf{U}_n$  such that (14) holds.

However, we are able proof this conjecture only in the case where  $\Phi_n$  or rather its projective distribution  $\lambda$  are rotational invariant, i.e.  $\lambda = \varpi_n$ . In this case *any* probability measure  $\mathbb{P}$  in (14) will again produce a rotational invariant measure  $\tilde{\lambda}$  on  $\mathbb{S}^{n-1}$ , so that in fact  $\tilde{\lambda} = \varpi_n$ .

**Corollary 6.** The following statements on an orthonormal system  $\Psi_n \subset L_2(\nu)$  and its projective distribution  $\tilde{\lambda}$  are equivalent.

- (i)  $\lambda = \omega_n$ .
- (ii)  $\tilde{\lambda}$  is rotational invariant.
- (iii)  $\pi(\cdot|\Psi_n)$  is minimal in the sense, that

$$\pi(T|\Psi_n) \leq \pi(T|\Phi_n),$$

however we choose the operator T and the Hilbert space  $L_2(\mu)$ , and the orthonormal system  $\Phi_n \subset L_2(\mu)$ .

**Proof.** That (i) is equivalent to (ii) is just the fact that  $\varpi_n$  is the only rotational invariant measure on  $\mathbb{S}^{n-1}$  of total mass n.

(i)  $\Longrightarrow$  (iii): Let us consider an orthonormal system  $\Phi_n \subset L_2(\mu)$  with projective distribution  $\lambda$ . Define

$$\tilde{\Phi}_n: \Omega \times \mathbf{U}_n \longrightarrow \mathbb{C}^n,$$

$$(t, V) \longmapsto V\Phi_n(t)$$

regarded as an orthonormal system with respect to the product measure  $\mu \otimes m_{\mathbf{U}_n}$  (see above). As a matter of fact  $\tilde{\Phi}_n$  is rotational invariant, hence its projective distribution coincides with  $\varpi_n$  and we get

$$\pi(T|\tilde{\Phi}_n) = \pi(T|\Psi_n) \qquad (T \in \mathcal{L}),$$

provided (i) holds. By the preceeding lemma,

$$\pi(T|\tilde{\Phi}_n) \le \pi(T|\Phi_n) \qquad (T \in \mathcal{L}).$$

Altogether we have show (iii).

(iii)  $\Longrightarrow$  (i): We know that  $\Pi_n \subset L_2(\varpi_n)$  is rotational invariant, thus  $\pi(U|[\Pi_n, \varpi_n]) \leq \pi(U|[\Phi_n, \mu])$ . Assuming (iii) we even have equality, i.e.  $\pi(U|[\Phi_n, \mu]) = \pi(U|[\Pi_n, \varpi_n])$  for all  $U: \ell_2^n \to X$  and all banach spaces X. By rotational invariance the map

$$\mathbf{U}_n \to \mathbb{R}_+, V \mapsto \|UV\Pi_N\|_{L_2^X(\varpi_n)}$$

is constant equal to  $\pi(U|[\Pi_n, \varpi_n])$ . Recall that

$$\left(\int \|UV\Pi_n\|_{L_2^X(\lambda)}^2 m_{\mathbf{U}_n}(dV)\right)^{1/2} = \pi(U|[\Pi_n, \varpi_n]).$$

Hence, assuming that the map

$$\mathbf{U}_n \to \mathbb{R}_+, V \mapsto \|UV\Pi_n\|_{L_2^X(\lambda)}$$

was not contant we had the contradiction

$$\pi(U|[\Phi_n, \mu]) = \sup_{V \in \mathbf{U}_n} \|UV\Pi_n\|_{L_2^X(\lambda)} > \left(\int \|UV\Pi_n\|_{L_2^X(\lambda)}^2 m_{\mathbf{U}_n}(dV)\right)^{1/2} = \pi(U|[\Pi_n, \varpi_n]).$$

This proves in particular

$$||U\Pi_n||_{L_2^X(\lambda)} = ||U\Pi_n||_{L_2^X(\varpi_n)}$$

and since U was arbitrary we are done by virtue of theorem 6.

Q.E.D.

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