

# Onset of convection in porous layers salted from above and below

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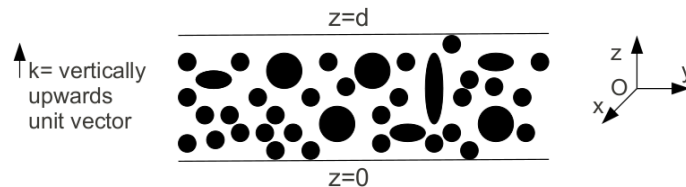
**Abstract.** For a porous layer heated from below and salted from above and below, the non existence of subcritical instabilities and conditions of global stability - for special values of the Prandtl numbers - are found.

**Keywords:** Multi-component fluid mixtures, Porous media, Convection, Stability.

## 1 Introduction and aims

A porous medium is schematized via a body (generally rigid and called *skeleton*) having interconnected pores everywhere. Generally, the fluid occupying the pores is a mixture since are dissolved in chemical species (“salts”) and the layer is embedded in a temperature field.

The behaviour of convective-diffusive fluid mixtures in porous layer presents a picture of behaviours increasing with the number of components. Although the



subject of double-diffusive convection is still a very active research area [1]-[22], the same subject with more than two components, although more difficult – in the past as nowadays has also attracted the attention of many authors [23]-[30].

The present paper is concerned with an horizontal layer heated from below and salted by two salts, either from below (“salt 1”) or from above (“salt 2”).

Denoting by

$$\begin{cases} T = \text{temperature field, } C_i = \text{concentration field of the "salt } i", (i = 1, 2) \\ \mathbf{v} = \text{seepage velocity, } p = \text{pressure field,} \end{cases} \quad (1)$$

in the case of the boundary conditions

$$\begin{cases} T(0) = T_1, \quad T(d) = T_2, \quad T_1 - T_2 > 0, \\ C_i(0) = C_{il}, \quad C_i(d) = C_{iu}, \quad (i = 1, 2), \\ \mathbf{v} \cdot \mathbf{k} = 0, \quad \text{at } z = 0, z = d, \end{cases} \quad (2)$$

it follows that the perturbations  $(\mathbf{u}, \Phi_1, \Phi_2, \Pi)$  to the conduction solution {cfr. [29]}, with

$$\begin{cases} \mathbf{u} = \text{perturbation to } \mathbf{v}, \\ \Phi_i = \text{perturbation to } C_i, \\ \Pi = \text{perturbation to } p, \end{cases} \quad (3)$$

are governed by

$$\begin{cases} \nabla \Pi = -\mathbf{u} + (R\theta - R_1\Phi_1 - R_2\Phi_2)\mathbf{k}, \\ \nabla \cdot \mathbf{u} = 0, \\ \theta_t + \mathbf{u} \cdot \nabla \theta = R\omega + \Delta \theta, \\ P_1(\Phi_{1t} + \mathbf{u} \cdot \nabla \Phi_1) = R_1\omega + \Delta \Phi_1, \\ P_2(\Phi_{2t} + \mathbf{u} \cdot \nabla \Phi_2) = -R_2\omega + \Delta \Phi_2, \\ \omega = \theta = \Phi_1 = \Phi_2 = 0, \quad \text{on } z = 0, z = 1, \end{cases} \quad (4)$$

$$\omega = \theta = \Phi_1 = \Phi_2 = 0, \quad \text{on } z = 0, z = 1, \quad (5)$$

with

$$\begin{cases} \omega = \mathbf{u} \cdot \mathbf{k}, \\ R = \text{Rayleigh thermal number,} \\ R_i = \text{Rayleigh concentration number of "salt } i". \end{cases} \quad (6)$$

Assuming - as it is normally done - that

- i)  $\mathbf{u} = (u, v, \omega), \theta, \Phi_1, \Phi_2$  are periodic in the  $x$  and  $y$  directions respectively of periods  $2\pi/a_x, 2\pi/a_y$ ;
- ii)  $\Omega = [0, 2\pi/a_x] \times [0, 2\pi/a_y] \times [0, 1]$  is the periodicity cell;

- iii)  $\mathbf{u}, \theta, \Phi_1, \Phi_2$  belong to  $W^{2,2}(\Omega)$  and are such that all their first derivatives and second spatial derivatives can be expanded in Fourier series uniformly convergent in  $\Omega$ ,

our aim - according to the results obtained in {[29]-[30],[33]} - is to show that when the layer is salted from below by “salt 1” and from above by “salt 2”, then

- 1) do not exist subcritical instabilities;
- 2) exist physically relevant values of the “salts” Prandtl numbers such that the triply diffusive-convection can be reduced rigorously to the double diffusive-convection and the global stability condition is given by  $R^2 < R_C^2$  with

$$\begin{cases} R_c^2 = \min \left[ R_1^2 - \frac{R_2^2}{P_2} + 4\pi^2 \left( 1 + \frac{1}{P_2} \right), R_1^2 - R_2^2 + 4\pi^2 \right], \\ \text{when } P_1 = 1 \end{cases}, \quad (7)$$

$$\begin{cases} R_c^2 = \min \left[ \frac{R_1^2}{P_1} - R_2^2 + 4\pi^2 \left( 1 + \frac{1}{P_1} \right), R_1^2 - R_2^2 + 4\pi^2 \right], \\ \text{when } P_2 = 1, \end{cases}, \quad (8)$$

$$\begin{cases} R_c^2 = \min \left[ \frac{1}{P} (R_1^2 - R_2^2) + 4\pi^2 \left( 1 + \frac{1}{P} \right), R_1^2 - R_2^2 + 4\pi^2 \right], \\ \text{when } P_1 = P_2 = P. \end{cases}, \quad (9)$$

Section 2 is devoted to the boundary value problem of the problem at stake. The (Routh Hurwitz) conditions of linear stability are found in the subsequent Section while Sections 4-5 are devoted to the non existence of subcritical instabilities. Finally, (7)-(9) are shown in Section 6.

## 2 The boundary value problem at stake

We recall here a basic theorem - which proof is given either in [29] or [31] - concerned with the main boundary value problem (4)<sub>1</sub>-(4)<sub>2</sub>-(5).

**Theorem 1.** *Let  $(\mathbf{u}, \theta, \Phi_1, \Phi_2)$  be solution of the b.v.p.*

$$\begin{cases} \nabla \Pi = -\mathbf{u} + (R\theta - R_1\Phi_1 - R_2\Phi_2)\mathbf{k}, \\ \nabla \cdot \mathbf{u} = 0, \end{cases} \quad (10)$$

$$\omega = \theta = \Phi_1 = \Phi_2 = 0, \quad z = 0, 1, \quad (11)$$

then:

i)  $(\mathbf{u}, \theta, \Phi_1, \Phi_2)$  is solution of the b.v.p.

$$\begin{cases} \Delta\omega = \Delta_1(R\theta - R_1\Phi_1 - R_2\Phi_2), & \text{in } \Omega, \\ \mathbf{u} = \theta = \Phi_1 = \Phi_2 = 0, & \text{on } z = 0, 1, \\ \Delta_1 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}. \end{cases} \quad (12)$$

ii) a complete orthogonal system of solutions of (10) is given by

$$\begin{cases} \tilde{\omega}_n = \eta_n(R\tilde{\theta}_n - R_1\tilde{\Phi}_{1n} - R_2\tilde{\Phi}_{2n}), \\ \mathbf{u}_n = \frac{1}{a^2} \left( \frac{\partial^2 \tilde{\omega}_n}{\partial x \partial z} \mathbf{i} + \frac{\partial^2 \tilde{\omega}_n}{\partial y \partial z} \mathbf{j} \right) + \tilde{\omega}_n \mathbf{k}, \end{cases} \quad (13)$$

with

$$\begin{cases} a^2 = a_x^2 + a_y^2, \quad \xi_n = a^2 + n^2\pi^2, \quad \eta_n = \frac{a^2}{\xi_n}, \\ \omega = \sum_{1}^{\infty} \tilde{\omega}_n = \sum_{1}^{\infty} \omega_n(x, y, t) \sin(n\pi z), \\ \mathbf{u} = \sum_{1}^{\infty} \mathbf{u}_n = \sum_{1}^{\infty} (\tilde{u}_n \mathbf{i} + \tilde{v}_n \mathbf{j} + \tilde{\omega}_n \mathbf{k}), \\ \theta = \sum_{1}^{\infty} \tilde{\theta}_n = \sum_{1}^{\infty} \theta_n(x, y, t) \sin(n\pi z), \\ \Phi_i = \sum_{1}^{\infty} \tilde{\Phi}_{in} = \sum_{1}^{\infty} \Phi_{in}(x, y, t) \sin(n\pi z). \end{cases} \quad (14)$$

**Remark 1.** By virtue of theorem 1 the independent scalar unknown fields  $(u, v, \omega, \theta, \Phi_1, \Phi_2)$  are reduced to  $(\theta, \Phi_1, \Phi_2)$ .

### 3 Linear instability

Linearizing (4) and taking into account that by virtue of theorem 1, it turns out that

$$\Delta\varphi = - \sum_{1}^{\infty} \xi_n \varphi_n, \quad \varphi \in (\theta, \Phi_1, \Phi_2), \quad (15)$$

one obtains

$$\begin{cases} \theta_t = \sum_{n=1}^{\infty} (a_{1n}\theta_n + a_{2n}\Phi_{1n} + a_{3n}\Phi_{2n}), \\ \Phi_{1t} = \sum_{n=1}^{\infty} (b_{1n}\theta_n + b_{2n}\Phi_{1n} + b_{3n}\Phi_{2n}), \\ \Phi_{2t} = \sum_{n=1}^{\infty} (c_{1n}\theta_n + c_{2n}\Phi_{1n} + c_{3n}\Phi_{2n}), \end{cases} \quad (16)$$

with

$$\begin{cases} a_{1n} = R^2\eta_n - \xi_n, & a_{2n} = -RR_1\eta_n, & a_{3n} = -RR_2\eta_n, \\ b_{1n} = \frac{RR_1}{P_1}\eta_n, & b_{2n} = -\frac{(R_1^2\eta_n + \xi_n)}{P_1}, & b_{3n} = -\frac{R_1R_2}{P_1}\eta_n, \\ c_{1n} = -\frac{RR_2}{P_2}\eta_n, & c_{2n} = \frac{R_1R_2}{P_2}\eta_n, & c_{3n} = \frac{R_2^2\eta_n - \xi_n}{P_2}. \end{cases} \quad (17)$$

Setting

$$\begin{cases} \theta_n = \xi_{0n}(t)F(x, y) \sin(n\pi z), \\ \Phi_{in} = \xi_{in}(t)F(x, y) \sin(n\pi z), \end{cases} \quad (18)$$

by virtue of

$$\int_0^1 \sin(n\pi z) \sin(m\pi z) dz = \begin{cases} 0, & n \neq m \\ \frac{1}{2}, & n = m \end{cases} \quad (19)$$

(16) implies

$$\begin{cases} \frac{d\xi_{0n}}{dt} = a_{1n}\xi_{0n} + a_{2n}\xi_{1n} + a_{3n}\xi_{2n}, \\ \frac{d\xi_{1n}}{dt} = b_{1n}\xi_{0n} + b_{2n}\xi_{1n} + b_{3n}\xi_{2n}, \\ \frac{d\xi_{2n}}{dt} = c_{1n}\xi_{0n} + c_{2n}\xi_{1n} + c_{3n}\xi_{2n}. \end{cases} \quad (20)$$

Setting

$$\mathcal{L}_n = \begin{pmatrix} a_{1n} & a_{2n} & a_{3n} \\ b_{1n} & b_{2n} & b_{3n} \\ c_{1n} & c_{2n} & c_{3n} \end{pmatrix}$$

it easily follows that the characteristic equation of the  $\mathcal{L}_n$  eigenvalues  $\lambda_n$  is

$$\lambda_n^3 - \text{I}_{1n}\lambda_n^2 + \text{I}_{2n}\lambda_n - \text{I}_{3n} = 0, \quad (21)$$

with  $I_{1n}, I_{2n}, I_{3n}$  given by

$$\begin{cases} I_{1n} = a_{1n} + b_{2n} + c_{3n} = \lambda_{1n} + \lambda_{2n} + \lambda_{3n}, \\ I_{2n} = \begin{vmatrix} a_{1n} & a_{2n} \\ b_{1n} & b_{2n} \end{vmatrix} + \begin{vmatrix} a_{1n} & a_{3n} \\ c_{1n} & c_{3n} \end{vmatrix} + \begin{vmatrix} b_{2n} & b_{3n} \\ c_{2n} & c_{3n} \end{vmatrix}, \\ I_{3n} = \begin{vmatrix} a_{1n} & a_{2n} & a_{3n} \\ b_{1n} & b_{2n} & b_{3n} \\ c_{1n} & c_{2n} & c_{3n} \end{vmatrix}. \end{cases} \quad (22)$$

By virtue of the Routh-Hurwitz stability-conditions [31], the following theorem holds.

**Theorem 2.** *The conduction solution is linearly stable if and only if,  $\forall n \in \mathbb{N}$ , the inequalities*

$$I_{1n} < 0, \quad I_{3n} < 0, \quad I_{1n}I_{2n} - I_{3n} < 0, \quad (23)$$

hold.

Since (23) requires  $I_{2n} > 0$ , in view of

$$\begin{cases} I_{1n} = \left[ R^2 - \frac{R_1^2}{P_1} + \frac{R_2^2}{P_2} - \left( 1 + \frac{1}{P_1} + \frac{1}{P_2} \right) \frac{\xi_n}{\eta_n} \right] \eta_n, \\ I_{2n} = \left[ \left( \frac{1}{P_1} + \frac{1}{P_2} + \frac{1}{P_1 P_2} \right) \frac{\xi_n}{\eta_n} + \frac{1}{P_1} \left( 1 + \frac{1}{P_2} \right) R_1^2 - \frac{1}{P_2} \left( 1 + \frac{1}{P_1} \right) R_2^2 + \right. \\ \quad \left. - \left( \frac{1}{P_1} + \frac{1}{P_2} \right) R^2 \right] \xi_n \eta_n, \\ I_{3n} = \frac{1}{P_1 P_2} \left( R^2 - R_1^2 + R_2^2 - \frac{\xi_n}{\eta_n} \right) \eta_n \xi_n^2, \\ \inf_{(a^2, n) \in \mathbb{R}^+ \times \mathbb{N}} \frac{\xi_n}{\eta_n} = 4\pi^2, \end{cases} \quad (24)$$

it follows that

**Theorem 3.** *The conduction solution is linearly stable only if*

$$R_{C_i}^2 > 0, \quad (i = 1, 2, 3), \quad R^2 < R_C^2, \quad (25)$$

with

$$\left\{ \begin{array}{l} R_{C_1}^2 = \frac{R_1^2}{P_1} - \frac{R_2^2}{P_2} + 4\pi^2 \left( 1 + \frac{1}{P_1} + \frac{1}{P_2} \right), \\ R_{C_2}^2 = \frac{1}{P_1 + P_2} [(1 + P_2)R_1^2 - (1 + P_1)R_2^2 + 4\pi^2(1 + P_1 + P_2)], \\ R_{C_3}^2 = R_1^2 - R_2^2 + 4\pi^2, R_C^2 = \min(R_{C_1}^2, R_{C_2}^2, R_{C_3}^2). \end{array} \right. \quad (26)$$

#### 4 Preliminaries to nonexistence of subcritical instabilities

**Lemma 1.** *Let  $\lambda_1$  be a real eigenvalue of the matrix*

$$L = \begin{pmatrix} \alpha_{11} & \alpha_{12} & \alpha_{13} \\ \alpha_{21} & \alpha_{22} & \alpha_{23} \\ \alpha_{31} & \alpha_{32} & \alpha_{33} \end{pmatrix}, \quad \left( \begin{array}{l} \alpha_{ij} = \text{const} \in \mathbb{R} \\ i, j = 1, 2, 3 \end{array} \right) \quad (27)$$

and let  $\tilde{\mathbf{U}} = (1, \tilde{U}_2, \tilde{U}_3)$  be an associated eigenvector. Then the transformation

$$\mathbf{X} = L_1 \mathbf{Z}, \quad (28)$$

with

$$\mathbf{X} = (X_1, X_2, X_3)^T, \quad \mathbf{Z} = (Z_1, Z_2, Z_3)^T, \quad L_1 = \begin{pmatrix} 1 & 0 & 0 \\ \tilde{U}_2 & 1 & 0 \\ \tilde{U}_3 & 0 & 1 \end{pmatrix} \quad (29)$$

reduces the ternary system

$$\frac{d\mathbf{X}}{dt} = L\mathbf{X} + \mathbf{F}, \quad (30)$$

with  $(\mathbf{F})_{\mathbf{X}=0} = 0$ , to

$$\frac{d\mathbf{Z}}{dt} = \tilde{L}\mathbf{Z} + \tilde{\mathbf{F}}, \quad (31)$$

$$\tilde{L} = \begin{pmatrix} \lambda_1 & \tilde{\alpha}_{12} & \tilde{\alpha}_{13} \\ 0 & \tilde{\alpha}_{22} & \tilde{\alpha}_{23} \\ 0 & \tilde{\alpha}_{32} & \tilde{\alpha}_{33} \end{pmatrix}, \quad \tilde{\mathbf{F}} = (\tilde{F}_1, \tilde{F}_2, \tilde{F}_3)^T. \quad (32)$$

$$\left\{ \begin{array}{l} Z_1 = X_1, Z_2 = X_2 - \tilde{U}_2 X_1, Z_3 = X_3 - \tilde{U}_3 X_1, \\ \tilde{F}_1 = F, \tilde{F}_2 = F_2 - \tilde{U}_2 F_1, \tilde{F}_3 = F_3 - \tilde{U}_3 F_1 \end{array} \right. \quad (33)$$

$$\begin{cases} \tilde{\alpha}_{12} = \alpha_{12}, \tilde{\alpha}_{13} = \alpha_{13}, \\ \tilde{\alpha}_{22} = \alpha_{22} - \tilde{U}_2 \alpha_{12}, \tilde{\alpha}_{23} = \alpha_{23} - \tilde{U}_2 \alpha_{13}, \\ \tilde{\alpha}_{32} = \alpha_{32} - \tilde{U}_3 \alpha_{12}, \tilde{\alpha}_{33} = \alpha_{33} - \tilde{U}_3 \alpha_{13} \end{cases} \quad (34)$$

$$\tilde{\alpha}_{22} + \tilde{\alpha}_{33} = \lambda_2 + \lambda_3, \quad \tilde{\alpha}_{22}\tilde{\alpha}_{33} - \tilde{\alpha}_{23}\tilde{\alpha}_{32} = \lambda_2\lambda_3, \quad (35)$$

$\lambda_2, \lambda_3$  being other eigenvalues of  $L$ .

**Proof.** The proof, based on [32, pp.194-197], can be found in [30], [33].

**Lemma 2.** Let the eigenvalues  $\lambda_i$ , ( $i = 1, 2, 3$ ) of

$$L = \begin{pmatrix} \alpha_{11} & \alpha_{12} & \alpha_{13} \\ \alpha_{21} & \alpha_{22} & \alpha_{23} \\ \alpha_{31} & \alpha_{32} & \alpha_{33} \end{pmatrix} \quad (36)$$

have negative real part and let  $\lambda_1 < 0$  and

$$\Psi = (\tilde{A}_1 Z_2 - \tilde{A}_3 Z_3) \tilde{F}_2 + (\tilde{A}_2 Z_3 - \tilde{A}_3 Z_2) \tilde{F}_3 + Z_1 \tilde{F}_1 = 0, \quad (37)$$

with

$$\begin{cases} \tilde{A}_1 = \lambda_2 \lambda_3 + \tilde{\alpha}_{32}^2 + \tilde{\alpha}_{33}^2, & \tilde{A}_2 = \lambda_2 \lambda_3 + \tilde{\alpha}_{22}^2 + \tilde{\alpha}_{23}^2, \\ \tilde{A}_3 = \tilde{\alpha}_{22}\tilde{\alpha}_{32} + \tilde{\alpha}_{23}\tilde{\alpha}_{33}. \end{cases} \quad (38)$$

Then the function

$$\tilde{W} = \frac{1}{2} [Z_1^2 + \lambda_2 \lambda_3 (Z_2^2 + Z_3^2) + (\tilde{\alpha}_{22} Z_3 - \tilde{\alpha}_{32} Z_2)^2 + (\tilde{\alpha}_{23} Z_3 - \tilde{\alpha}_{33} Z_2)^2], \quad (39)$$

has - along

$$\frac{d\mathbf{Z}}{dt} = \tilde{L}\mathbf{Z} + \tilde{\mathbf{F}}, \quad (40)$$

the temporal derivative given by

$$\frac{d\tilde{W}}{dt} = \frac{1}{2} [\lambda_1 Z_1^2 + (\lambda_2 + \lambda_3) \lambda_2 \lambda_3 (Z_2^2 + Z_3^2)] < 0. \quad (41)$$

The null solution of (40) and hence of (30) is globally stable and subcritical instabilities do not exist.

**Proof.** A detailed proof can be found in [30], [33].

**Remark 2.** The eigenvalues of the matrix

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} \\ 0 & a_{22} & a_{23} \\ 0 & a_{32} & a_{33} \end{pmatrix}$$



have negative real part if and only if

$$a_{11} < 0, I = a_{22} + a_{33} < 0, A = a_{22}a_{33} - a_{32}a_{23}.$$

(cfr. Remark 2.5 of [30]).

## 5 Nonexistence of subcritical instabilities and global stability

Following [33], we set

$$S_m^{(\theta)} = \sum_{n=1}^m \theta_n, S_m^{(\Phi_i)} = \sum_{n=1}^m \Phi_{in}, \mathbf{U}_m = \sum_{n=1}^m \mathbf{u}_n, \quad (42)$$

$$\theta = \lim_{m \rightarrow \infty} S_m^{(\theta)}, \Phi_i = \lim_{m \rightarrow \infty} S_m^{(\Phi_i)}, (i = 1, 2). \quad (43)$$

The nonexistence of subcritical instabilities and the global stability is guaranteed by showing that the asymptotic stability of the null solution of

$$\left\{ \begin{array}{l} \frac{d}{dt} S_m^{(\theta)} = \sum_{n=1}^m (a_{1n} \theta_n + a_{2n} \Phi_{1n} + a_{3n} \Phi_{2n}) - \mathbf{U}_m \cdot \nabla S_m^{(\theta)}, \\ \frac{d}{dt} S_m^{(\Phi_1)} = \sum_{n=1}^m (b_{1n} \theta_n + b_{2n} \Phi_{1n} + b_{3n} \Phi_{2n}) - \mathbf{U}_m \cdot \nabla S_m^{(\Phi_1)}, \\ \frac{d}{dt} S_m^{(\Phi_2)} = \sum_{n=1}^m (c_{1n} \theta_n + c_{2n} \Phi_{1n} + c_{3n} \Phi_{2n}) - \mathbf{U}_m \cdot \nabla S_m^{(\Phi_2)}, \end{array} \right. \quad (44)$$

$$\theta_n = \Phi_{1n} = \Phi_{2n} = 0, \forall n \in \{1, \dots, m\} \text{ for } z = 0, 1. \quad (45)$$

$$\theta_n(0) = \theta_n^{(0)}, \Phi_{in}(0) = \Phi_{in}^{(0)}, i = 1, 2, n \in \{1, \dots, m\}. \quad (46)$$

$\forall m \in \mathbb{N}$ , is guaranteed by (23). On the other hand, introducing the evolution system governing the  $n$ -th component of the of the perturbation  $(\theta, \Phi_1, \Phi_2)$

$$\left\{ \begin{array}{l} \frac{\partial}{\partial t} \theta_n = a_{1n} \theta_n + a_{2n} \Phi_{1n} + a_{3n} \Phi_{2n} - \mathbf{U}_m \cdot \nabla \theta_n, \\ \frac{\partial}{\partial t} \Phi_{1n} = b_{1n} \theta_n + b_{2n} \Phi_{1n} + b_{3n} \Phi_{2n} - \mathbf{U}_m \cdot \nabla \Phi_{1n}, \\ \frac{\partial}{\partial t} \Phi_{2n} = c_{1n} \theta_n + c_{2n} \Phi_{1n} + c_{3n} \Phi_{2n} - \mathbf{U}_m \cdot \nabla \Phi_{2n}, \end{array} \right. \quad (47)$$

$$\left\{ \begin{array}{l} \mathbf{U}_m = \sum_{n=1}^m \mathbf{u}_n, \mathbf{u}_n = \frac{1}{a^2} \left( \frac{\partial^2 \omega_n}{\partial x \partial z} \mathbf{i} + \frac{\partial^2 \omega_n}{\partial y \partial z} \mathbf{j} + \omega_n \mathbf{k} \right), \\ \omega_n = \tilde{\omega}_n(x, y, t) \sin(n\pi z), \theta_n = \tilde{\theta}_n(x, y, t) \sin(n\pi z), \\ \Phi_{in} = \tilde{\Phi}_{in}(x, y, t) \sin(n\pi z), i = 1, 2, n \in \{1, \dots, m\} \end{array} \right. \quad (48)$$

(44) are immediately obtained by adding with respect to  $n$  from  $n = 1$  to  $n = m$  each equations of (47). Therefore the nonexistence of subcritical instabilities and the global stability is guaranteed by showing that (23) imply the asymptotic stability of the null solution of (45)-(48)  $\forall m \in \mathbb{N}$ .

**Theorem 4.** *Let (23) hold. Then, for any  $m \in \mathbb{N}$ , the zero solution of (45)-(48) is asymptotically stable for any initial data*

**Proof.** Denoting by  $\lambda_{ni}$ , ( $i = 1, 2, 3$ ), the roots of (21), (23) guarantee that  $\lambda_{ni}$  have negative real part and at least one - say  $\lambda_{n1}$  - be a negative real number. Then denoting by  $\tilde{\mathbf{U}}_n = (1, \tilde{U}_{n2}, \tilde{U}_{n3})$  an eigenvector associated to  $\lambda_{n1}$ , Lemma 1 can be applied by setting

$$\left\{ \begin{array}{l} Z_{n1} = \theta_n, Z_{n2} = \Phi_{1n} - \tilde{U}_{n2}\theta_n, Z_{n3} = \Phi_{2n} - \tilde{U}_{n3}\theta_n, \\ F_1 = \mathbf{U}_m \cdot \nabla \theta_n, F_2 = \mathbf{U}_m \cdot \nabla \Phi_{1n}, F_3 = \mathbf{U}_m \cdot \nabla \Phi_{2n}, \\ \tilde{F}_1 = F_1, \tilde{F}_2 = F_2 - \tilde{U}_{n2}F_1, \tilde{F}_3 = F_3 - \tilde{U}_{n3}F_1 \end{array} \right. \quad (49)$$

Let

$$\tilde{V}_n = \int_{\Omega} \tilde{W}_n d\Omega, \quad (50)$$

with  $\tilde{W}_n$  given by (39) with  $\lambda_{ni}$  at the place of  $\lambda_i$ . Then - instead of (41) - one has to show that

$$\tilde{\Psi} = \langle \tilde{A}_{1n}Z_{n2} - \tilde{A}_{3n}Z_{n3}, \tilde{F}_2 \rangle + \langle \tilde{A}_{2n}Z_{n3} - \tilde{A}_{3n}Z_{n2}, \tilde{F}_3 \rangle + \langle Z_{n1}, \tilde{F}_1 \rangle = 0, \quad (51)$$

with  $\tilde{A}_{1n}, \tilde{A}_{2n}, \tilde{A}_{3n}$  constants.

In view of (49) it follows that  $Z_{ni}$ , ( $i = 1, 2, 3$ ), is of the kind

$$Z_{ni} = \tilde{Z}_{ni}(x, y, t) \sin(n\pi z), \quad (52)$$

$$\mathbf{U}_m \cdot \nabla \theta_n = \sum_{p=1}^m \left[ \frac{p\pi}{a^2} \left( \frac{\partial \tilde{\omega}_p}{\partial x} \frac{\partial \tilde{\theta}_n}{\partial x} + \frac{\partial \tilde{\omega}_p}{\partial y} \frac{\partial \tilde{\theta}_p}{\partial x} \right) \cos(p\pi z) \sin(n\pi z) + \right. \quad (53)$$

$$\left. n\pi \tilde{\omega}_p \tilde{\theta}_p \sin(p\pi z) \cos(n\pi z) \right]$$

and hence

$$\langle Z_m, \tilde{F}_1 \rangle = \langle \frac{\tilde{Z}_{n1} \sin(n\pi z)}{U_{n1}^*}, \mathbf{U}_m \cdot \nabla \theta_n \rangle. \quad (54)$$

Since it easily turns out that

$$\int_0^1 \sin(q\pi z) \cos(p\pi z) \sin(n\pi z) dz = 0, \text{ for } p + q \neq n. \quad (55)$$

But one easily verifies that all the other scalar products appearing in  $\tilde{\Psi}$  are linear combinations of terms of kind (54) (with  $\Phi_{in}$  at the place of  $\theta_n$ ) and hence by virtue of (55) it turn out that  $\tilde{\Psi} = 0$ .

## 6 Proof of (7)

In the case  $P_1 = 1$ , (4) reduces to

$$\begin{cases} \nabla p = -\mathbf{u} + (R\theta - R_1\Phi_1 - R_2\Phi_2)\mathbf{k}, \\ \theta_t = R\omega + \Delta\theta - \mathbf{u} \cdot \nabla\theta, \\ \Phi_{1t} = R_1\omega + \Delta\Phi_1 - \mathbf{u} \cdot \nabla\Phi_1, \\ \Phi_{2t} = -\frac{R_2}{P_2}\omega + \frac{1}{P_2}\Delta\Phi_1 - \frac{\mathbf{u}}{P_2} \cdot \nabla\Phi_2. \end{cases} \quad (56)$$

Setting

$$\varphi = R_1\theta - R\Phi_1 = 0 \Leftrightarrow \Phi_1 = \frac{1}{R}(R_1\theta - \varphi), \quad (57)$$

it follows that

$$\nabla p = -\mathbf{u} + \left( \frac{R^2 - R_1^2}{R}\theta + \frac{R_1}{R}\varphi - R_2\Phi_2 \right) \mathbf{k}, \quad (58)$$

$$\begin{cases} \varphi_t = \Delta\varphi - \mathbf{u} \cdot \nabla\varphi, \\ \theta_t = R\omega + \Delta\theta - \mathbf{u} \cdot \nabla\theta, \\ \Phi_{2t} = -\frac{R_2}{P_2}\omega + \frac{1}{P_2}\Delta\Phi_2 - \frac{\mathbf{u} \cdot \nabla\Phi_2}{P_2}. \end{cases} \quad (59)$$

In view of theorem 1, one obtains

$$\tilde{\omega}_n = \eta_n \left( \frac{R^2 - R_1^2}{R} \tilde{\theta}_n + \frac{R_1}{R} \tilde{\varphi}_n - R_2 \tilde{\Phi}_{2n} \right), \quad (60)$$

and hence

$$\left\{ \begin{array}{l} \varphi_t = \sum_1^{\infty} (\bar{\alpha}_{1n}\varphi_n + \bar{\alpha}_{2n}\theta_n + \bar{\alpha}_{3n}\Phi_{2n}) - \mathbf{u} \cdot \nabla\varphi, \\ \theta_t = \sum_1^{\infty} (\bar{\beta}_{1n}\varphi_n + \bar{\beta}_{2n}\theta_n + \bar{\beta}_{3n}\Phi_{2n}) - \mathbf{u} \cdot \nabla\theta, \\ \Phi_{2t} = \sum_1^{\infty} (\bar{\gamma}_{1n}\varphi_n + \bar{\gamma}_{2n}\theta_n + \bar{\gamma}_{3n}\Phi_{2n}) - \mathbf{u} \cdot \nabla\Phi_{2n}, \end{array} \right. \quad (61)$$

with

$$\left\{ \begin{array}{l} \bar{\alpha}_{1n} = -\xi_n, \quad \bar{\alpha}_{2n} = \bar{\alpha}_{3n} = 0, \\ \bar{\beta}_{1n} = R_1\eta_n, \bar{\beta}_{2n} = (R^2 - R_1^2)\eta_n - \xi_n, \bar{\beta}_{3n} = -RR_2\eta_n, \\ \bar{\gamma}_{1n} = -\frac{R_1R_2}{RP_2}\eta_n, \bar{\gamma}_{2n} = -\frac{R_2(R^2 - R_1^2)}{RP_2}\eta_n, \bar{\gamma}_{3n} = \frac{R_2^2\eta_n - \xi_n}{P_2}. \end{array} \right. \quad (62)$$

The auxiliary system, governing the  $n$ -th component of the fields  $(\varphi, \theta, \Phi_{2n})$  analogous to (47), can easily found to be

$$\left\{ \begin{array}{l} \frac{\partial}{\partial t}\varphi_n = -\xi_n\varphi_n + 0 + 0 - \mathbf{U}_m \cdot \nabla\varphi_n, \\ \frac{\partial}{\partial t}\theta_n = \bar{\beta}_{1n}\varphi_n + \bar{\beta}_{2n}\theta_n + \bar{\beta}_{3n}\Phi_{2n} - \mathbf{U}_m \cdot \nabla\theta_n, \\ \frac{\partial}{\partial t}\Phi_{2n} = \bar{\gamma}_{1n}\varphi_n + \bar{\gamma}_{2n}\theta_n + \bar{\gamma}_{3n}\Phi_{2n} - \mathbf{U}_m \cdot \nabla\Phi_{2n}. \end{array} \right. \quad (63)$$

Setting

$$\left\{ \begin{array}{l} \mathcal{I}_n = \bar{\beta}_{2n} + \bar{\gamma}_{3n} = \eta_n \left[ R^2 - R_1^2 + \frac{R_2^2}{P_2} - \left( 1 + \frac{1}{P_2} \right) \frac{\xi_n^2}{a^2} \right], \\ \mathcal{A}_n = \bar{\beta}_{2n}\bar{\gamma}_{3n} + \bar{\beta}_{3n}\bar{\gamma}_{2n} = \eta_n\xi_n \left[ -(R^2 - R_1^2) - R_2^2 - \frac{\xi_n^2}{a^2} \right], \end{array} \right. \quad (64)$$

$$\tilde{V}_n = \frac{1}{2} \int_{\Omega} \{ \varphi_n^2 + \mathcal{A}_n(\theta_n^2 + \Phi_{2n}^2) + (\bar{\beta}_{2n}\Phi_{2n} - \bar{\gamma}_{2n}\theta_n)^2 + (\bar{\beta}_{3n}\Phi_{2n} - \bar{\gamma}_{2n}\theta_n)^2 \} ds \quad (65)$$

it follows that

$$\frac{d\tilde{V}_n}{dt} \leq \frac{1}{2} \int_{\Omega} [-\xi_n \varphi_n^2 + \mathcal{I}_n \mathcal{A}_n (\theta_n^2 + \Phi_{2n}^2)] d\Omega \quad (66)$$

with

$$\xi_n = a^2 + n^2 \pi^2 \geq \pi^2. \quad (67)$$

Therefore

$$\begin{cases} \mathcal{I}_n < 0 \Leftrightarrow R^2 < R_1^2 - \frac{R_2^2}{P_2} + 4\pi^2 \left(1 + \frac{1}{P_2}\right) \\ \mathcal{A}_n > 0 \Leftrightarrow R^2 < R_1^2 - R_2^2 + 4\pi^2 \end{cases} \quad (68)$$

i.e. (7) guarantee the global stability.

**Remark 3.** We remark that:

- 1) The same procedure can be applied for obtaining (8)-(9) [29];
- 2) in the cases  $P_2 \geq 1$ ,  $P_1 \leq 1$ , (7)-(8) reduce to

$$R_G^2 = R_1^2 - R_2^2 + 4\pi^2. \quad (69)$$

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